

Adomian's Decomposition of Multi-Order Fractional Differential Equations

Ojo Gbenga Olayinka

Submitted to the
Institute of Graduate Studies and Research
in partial fulfillment of the requirements for the degree of

Master of Science
in
Applied Mathematics and Computer Science

Eastern Mediterranean University
July 2016
Gazimağusa, North Cyprus

Approval of the Institute of Graduate Studies and Research

Prof. Dr. Cem Tanova
Acting Director

I certify that this thesis satisfies the requirements as a thesis for the degree of Master of Science in Applied Mathematics and Computer Science.

Prof. Dr. Nazim Mahmudov
Chair, Department of Mathematics

We certify that we have read this thesis and that in our opinion it is fully adequate in scope and quality as a thesis for the degree of Master of Science in Applied Mathematics and Computer Science.

Prof. Dr. Nazim Mahmudov
Supervisor

Examining Committee

1. Prof. Dr. Nazim Mahmudov

2. Asst. Prof. Dr. Mustafa Kara

3. Asst. Prof. Dr. Suzan Buranay

ABSTRACT

Adomian's Decomposition Method (ADM) was introduced about three decades ago, it has proven to be efficient, reliable and easy to compute the solutions of non-linear and linear differential equations. It can also be used to compute various types of equations such as Boundary value problems, Integral equations, Equations arising in fluid flow e.t.c.

This thesis work presents the derivation of Adomian's decomposition algorithms and the possible solution of fractional differential equations of the multi-order type in the Caputo sense. It consist of four chapters, Chapter 1 contains a brief introduction of Adomian's Decomposition Method(ADM) and definitions, while the second chapter deals with basis proofs and methodology with respect to Adomian's Decomposition Method(ADM). In Chapter 3, we applied the method of solution to multi-order fractional differential equations. We then discuss the results and make conclusion in Chapter 4.

Keywords: Adomian's Algorithm, Caputo's Derivative, Multi-Order Fraction Differential Equation.

ÖZ

Adomian'ın Ayrıştırma Yöntemi üç yıl önce tanımlanmıştır. Bu yöntemin lineer olmayan diferansiyel denklemlerin çözümlerini hesaplamak için verimli, güvenilir ve kolay olduğu kanıtlanmıştır. Ayrıca bu yöntem sınır değer problemleri, Rntegel denklemleri ve sıvı akışkan denklemleri gibi denklemleri hesaplamak için kullanılır.

Bu tez çalışmasında Adomian'ın ayrıştırma yöntemi algoritmaları türetme ve Caputo tipli çok basamaklı fraksiyonel diferensiel denklemlerin olsai çözümleri ifade edilmiştir. Bu tez dört bölümden oluşmaktadır. İlk bölümde Adomian'ın Ayrıştırma Yöntemi hakkında gerekli temel bilgiler ve tanımlar verilmiştir. İkinci bölümde Adomian'ın ayrıştırma yöntemi'nin metodolojisi ve bu yöntemle ilgili temel kanıtlar verilmiştir.

Üçüncü bölümde ise bu yöntemi çok basamaklı kesirli diferansiyel denklemlerin çözümünde uyguladık. Dördüncü bölümde ise bulduğumuz sonuçları tartışıp ve sonucu yazdık.

Anahtar kelimeler: Adomian'ın ayrıştırma yöntemi, Caputo Derivasyon, Çok Basamakli Kesirli diferansiyel denklemler

DEDICATION

To My Family

ACKNOWLEDGMENT

My profound appreciation and gratitude goes to Prof. Dr. Nazim Mahmudov (my thesis advisor) for his continual support, corrections, dedication and encouragement during my thesis work, it is great honour working with you. Also I will like to express my sincere gratitude to my course advisor Professor. Dr. Sonuc Zorlu Ogurlu, you taught me how to chose my courses wisely. Also to the members of my thesis examination committee Asst. Prof. Dr. Mehmet Bozer and Asst. Prof. Dr. Suzan Buranay. Indeed I am grateful for the time you all have devoted to make this thesis work a reality, your assistance has been invaluable.

I would like to appreciate the management of Joseph Ayo Babalola University for the support and the encouragement I received to embark on my postgraduate studies also for granting my study leave with pay.

I wish to express my love to my wife (Omoboyede) and our child (Deborah) for the patient, perseverance and support during the program at Eastern Mediterranean University. Lastly I will like to appreciate my friends who have made my stay here a pleasant one. Olalekan Ayamolowo, Babalola Ademola, Reger Ahmed, Ahmed Hersi, Zahid Ali and Kawa Sardar.

LIST OF CONTENTS

ABSTRACT	iii
ÖZ	iv
DEDICATION	v
ACKNOWLEDGMENT	vi
1 INTRODUCTION	1
2 ADOMIAN'S DECOMPOSITION METHOD	4
2.1 The Gamma Function.....	4
2.2 Method of Solution	5
3 APPLICATIONS	10
3.1 Solutions of Some Examples	10
3.1.1 Example 1.....	10
3.1.2 Example 2.....	17
3.1.3 Example 3.....	23
3.1.4 Example 4.....	28
4 DISCUSSION OF RESULTS	40
4.1 Conclusion	40
REFERENCES	42

LIST OF FIGURES

Figure 1. Solution to Example 1.....	16
Figure 2. Solution to Example 2	22
Figure 3. Solution to Example 3	27
Figure 4. Solution to Example 4.....	38

Chapter 1

INTRODUCTION

This Chapter consist of Preliminary concept of Adomian's Decomposition Method (ADM) with some basic definitions. A new technique for solving Non-linear fractional differential equation was initiated by George Adomian in the 1980's, called Adomian's Decomposition Method (ADM) [6]. The procedure involves separating equations concern into Linear and Non-linear parts and treated accordingly with consideration of any given conditions. The non-linear part is decomposed into polynomial series called Adomian's polynomial and results are generated in form of a recursive series.

The issue of convergence of ADM is of great concern, several researchers investigated the convergence and concluded that the method is convergent, which produces a convergence series solution, truncating this series solution result to an approximate solution [9], [5], [7], [6].

Furthermore Charruault et al. [6] establish that the series produced by ADM is absolutely convergent as well as uniformly convergent. Since the series converges rapidly, having higher order of converge is desirable. Babolian and Bizar [5] provided a method to determine the order of convergence.

1.1 Definitions

Definition 1.1.1: Consider the following equation:

$$D_t^{\bar{\sigma}} = \frac{d^{\bar{\sigma}} y}{dt^{\bar{\sigma}}} = f\left(t, y(t), y_1^{\hat{\phi}}(t), y_2^{\hat{\phi}}(t), \dots, y_n^{\hat{\phi}}(t)\right) \quad (1)$$

subject to the incipient condition:

$$y^i(0) = \rho_i, \quad i = 0, 1, 2, \dots, n-1 \quad (2)$$

where $\bar{\sigma} \geq \hat{\phi} \geq \phi_{m-1} \geq \dots \geq \hat{\phi} \geq 0$, $n-1 \leq \bar{\sigma} \leq n$, $\forall n \in \mathbb{N}$.

These equations are called multi-order fractional derivative equation, the equation (1) and (2) are examined in Caputo sense using ADM technique as the method of solution, because it makes the given equation to have a unique solution. Caputo fractional integral operator is a modification of Riemman-liouville fractional integral operator. If considered in the sense of Riemman-liouville, it is necessary to describe the incipient conditions in terms of fractional integrals and derivatives. The advantage of ADM is the possible avoidance of discretization which provides a coherent numerical solution with high accuracy and minimal calculations, making it less expensive to compute.

Definition 1.1.2: The Riemman-Liouville fractional integral operator of $\bar{\sigma} \geq 0$ is express as:

$$j^{\bar{\sigma}} f(x) = \frac{1}{\Gamma(\bar{\sigma})} \int_0^x (x-t)^{\bar{\sigma}-1} f(t) dt, \quad x > 0, \quad \bar{\sigma} > 0, \quad (3)$$

$$j^0 f(x) = f(x). \quad (4)$$

The fractional derivative of $f(x)$ in Caputo's sense is express as:

$$D^{\bar{\sigma}} f(x) = j^{n-\bar{\sigma}} D^n f(x) = \frac{1}{\Gamma(n-\bar{\sigma})} \int_0^x (x-t)^{n-\bar{\sigma}-1} f^n dt \quad (5)$$

for $x > 0$, $n-1 < \check{\sigma} \leq n$, $\forall n \in m$, $f \in C_1^n$.

They both have various properties described in literatures [11].

Properties of the $j^{\hat{\phi}}$:

$$j^{\hat{\phi}} x^{\check{\sigma}} = \frac{\Gamma(\check{\sigma}+1)}{\Gamma(\hat{\phi}+\check{\sigma}+1)} x^{\hat{\phi}+\check{\sigma}} \quad (6)$$

$$j^{\hat{\phi}} j^{\check{\sigma}} f(x) = j^{\check{\sigma}} j^{\hat{\phi}} f(x) \quad (7)$$

$$j^{\hat{\phi}} j^{\check{\sigma}} = j^{\hat{\phi}+\check{\sigma}}. \quad (8)$$

Let $m-1 < \hat{\phi} < m$, $\forall m \in N$ and $f \in C_{\mu}^m$, $\mu \geq -1$, so:

$$j^{\hat{\phi}} f(x) = f(x) \quad (9)$$

$$j^{\hat{\phi}} D^{\hat{\phi}} = f(x) - \sum_{n=0}^{m-1} \frac{x^n}{n!} f^{(n)}(0) \quad (10)$$

Definition 1.1.3: A function $f(x); x > 0$ is contained in the space C_{μ} , $\mu \in R$,

$\ni k \in R$:

$$f(x_0) = x^k f_1'(x) \quad (11)$$

$\forall f_1(x) \in C[0, x]$, $C_{\mu} \subset C_{\beta}$ if $\check{\sigma} < \mu$

Chapter 2

ADOMIAN'S DECOMPOSITION METHOD

In this Chapter we considered an important special function known as the Gamma Function and briefly describe the method of solution.

Consider the following equation.

2.1 The Gamma Function

The Gamma Function $\Gamma(n)$ can be defined as:

$$\Gamma(n) = \int_0^{\infty} e^{-s} s^{n-1} ds, \quad n \in R \quad (12)$$

It is convergent on the plane $\text{Re}(n) > 0$.

Lemma 2.1.1: if $p \in C$ with $\text{Re}(n) > 0$ then

$$\Gamma(p+1) = p\Gamma(p) \quad (13)$$

Proof: Using integration by part:

$$\Gamma(n+1) = \int_0^{\infty} e^{-s} s^n ds = -e^{-s} s^n \Big|_0^{\infty} + n \int_0^{\infty} e^{-s} s^{n-1} ds = n\Gamma(n) \quad (14)$$

Where $\Gamma(1) = 1$ and for $n = 2, 3, \dots$

$$\Gamma(2) = 1\Gamma(1)$$

$$\Gamma(3) = 2\Gamma(2)$$

$$\Gamma(4) = 3\Gamma(3) \dots$$

$$\Gamma(n+1) = n\Gamma(n) = n(n-1)(n-2) \dots = n$$

2.2 Method of Solution

Equation (1) is express in Adomian's form and pattern as follows:

$$D_t^{\bar{\sigma}} y(t) + Ly(t) + Ny(t) = \rho(t) \quad (15)$$

L is the linear operator,

N is the non-linear operator,

$D_t^{\bar{\sigma}}$ is the fractional derivative of order $\bar{\sigma}$,

$\rho(t)$ is the source term.

ADM is base on applying $j^{\bar{\sigma}}$ to equation (15). Substitution of equation(17) into equation(15) we have:

$$D_t^{\bar{\sigma}} y(t) = \rho(t) - L \sum_{k=0}^{\infty} y_k(t) - \sum_{k=0}^{\infty} A_k \quad (16)$$

$$\text{Where } Ny(t) = \sum_{k=0}^{\infty} A_k \text{ and } Ly(t) = \sum_{k=0}^{\infty} y_k(t) \quad (17)$$

A_k is the Adomian's polynomial. We shall derive it by using Taylor series expansion with generalization of multi variable function

$$\text{Let } f = \varphi \left(\sum_{i=0}^{\infty} \lambda^i y_i \right) \quad (18)$$

Consider the power series expansion of the function $f(\lambda)$ about the point λ_0

$$f(\lambda) = A_0 + A_1(\lambda_* - \lambda_0) + A_2(\lambda_* - \lambda_0)^2 + A_3(\lambda_* - \lambda_0)^3 + \dots \quad (19)$$

We determine the values of $A_0, A_1, A_2, A_3, \dots$

$$\text{If } \lambda_* - \lambda_0 = 0 \Rightarrow \lambda_* = \lambda_0 \quad (20)$$

$$\Rightarrow f(\lambda_0 = A_0) \quad (21)$$

The derivative of equation (19) is as follows:

$$\frac{df(\lambda)}{d\lambda} = A_1 + 2A_2(\lambda_* - \lambda_0) + 3A_3(\lambda_* - \lambda_0)^2 + 4A_4(\lambda_* - \lambda_0)^3 + \dots \quad (22)$$

Similarly, if :

$$\lambda_* = \lambda_0, \frac{df(\lambda)}{d\lambda} = A_1 \Rightarrow A_1 = \left. \frac{df(\lambda)}{d\lambda} \right|_{\lambda=0}. \quad (23)$$

We consider again the second and third derivative after which we generalize.

$$\frac{d^2f(\lambda)}{d\lambda^2} = 2A_2 + 6A_3(\lambda_* - \lambda_0) + 12A_4(\lambda_* - \lambda_0)^2 + 60A_5(\lambda_* - \lambda_0)^3 + \dots \quad (24)$$

Similarly, if

$$\lambda_* = \lambda_0, \frac{d^2f(\lambda)}{d\lambda^2} = 2A_2 \Rightarrow 2A_2 = \frac{1}{2} \left(\left. \frac{d^2f(\lambda)}{d\lambda^2} \right|_{\lambda=0} \right) \quad (25)$$

$$\frac{d^3f(\lambda)}{d\lambda^3} = 6A_3(\lambda_* - \lambda_0) + 24A_4(\lambda_* - \lambda_0)^2 + 60A_5(\lambda_* - \lambda_0)^3 + 120A_6(\lambda_* - \lambda_0)^4 + \dots \quad (26)$$

Similarly, if :

$$\lambda_* = \lambda_0, \frac{d^3f(\lambda)}{d\lambda^3} = 6A_3 \Rightarrow A_3 = \frac{1}{6} \left(\left. \frac{d^3f(\lambda)}{d\lambda^3} \right|_{\lambda=0} \right). \quad (27)$$

If we continue in same manner, we obtain:

$$A_\rho = \frac{1}{\rho!} \left[\left(\left. \frac{d^\rho f(\lambda)}{d\lambda^\rho} \right|_{\lambda=0} \right) \right], \quad (28)$$

where $f = \varphi \left(\sum_{i=0}^{\infty} \lambda^i y_i \right)$ the multi- variable function, we have

$$A_\rho = \frac{1}{\rho!} \left[\left(\frac{d^\rho}{d\lambda^\rho} \varphi \left(\sum_{i=0}^{\infty} \lambda^i y_i \right) \right) \right]_{\lambda=0}, \quad (29)$$

these are the Adomian Algorithms.

Substitute equation (17) into (15) we get:

$$D_i^\sigma y(t) = g(t) - L \sum_{\rho=0}^{\infty} y_\rho(t) - \sum_{\rho=0}^{\infty} A_\rho, \quad (30)$$

but $j^\sigma D^\sigma = f(x) - \sum_{\rho=0}^{n-1} f^{(\rho)}(0^+) \frac{x^\rho}{\rho!}, x > 0$. operating j^σ on equation(30) we have:

$$y(t) = \sum_{\beta=0}^{n-1} y^{(\beta)}(0^+) \frac{t^\beta}{\beta!} + j^\sigma g(t) - j^\sigma L \sum_{\rho=0}^{\infty} y_\rho(t) - j^\sigma \sum_{\rho=0}^{\infty} A_\rho \quad (31)$$

$$\Rightarrow y(t) = \sum_{i=0}^{n-1} y^{(i)}(0^+) \frac{t^i}{i!} + j^\sigma g(t) - j^\sigma L y_\rho(t) - j^\sigma N y(t), \quad (32)$$

$$\text{where } y_0 = \sum_{i=0}^{n-1} y^{(i)}(0^+) \frac{t^i}{i!} + j^\sigma g(t). \quad (33)$$

Therefore :

$$y_1 = -j^\sigma L y_0 - j^\sigma A_0 \quad (34)$$

$$y_2 = -j^\sigma L y_1 - j^\sigma A_1 \quad (35)$$

$$y_3 = -j^\sigma L y_2 - j^\sigma A_2 \quad (36)$$

$$y_4 = -j^\sigma L y_3 - j^\sigma A_3 \dots \quad (37)$$

The result is given in series form:

$$y(t) = \sum_{\rho=0}^{\infty} y_\rho(t). \quad (38)$$

We generate the Adomian's Polynomial with the derived algorithms as follows:

$$A_\rho = \frac{1}{\rho!} \left[\frac{d^\rho}{d\eta^\rho} \varphi \left(\sum_{i=0}^{\infty} \eta^i y_i \right) \right]_{\eta=0} \quad (39)$$

when $\rho = 0$ we have:

$$A_0 = \frac{1}{0!} \left[\frac{d^0}{d\eta^0} \varphi(\eta^0 y_0) \right]_{\eta=0} = \varphi(y_0) \quad (40)$$

$\Rightarrow A_1 = \varphi'(y_0)$ when $\rho = 1$ we get:

$$A_1 = \frac{1}{1!} \left[\frac{d}{d\eta} \varphi \left(\sum_{i=0}^1 \eta^i y_i \right) \right]_{\eta=0} = 1 \left[\frac{d}{d\eta} \varphi(\eta y + \eta^0 y_0) \right]_{\eta=0} \quad (41)$$

$\Rightarrow A_2 = y_1 \varphi'(y_0)$, when $\rho = 2$ we get:

$$A_2 = \frac{1}{2!} \left[\frac{d^2}{d\eta^2} \varphi \left(\sum_{i=0}^2 \eta^i y_i \right) \right]_{\eta=0} = \frac{1}{2} \left[\frac{d^2}{d\eta^2} \varphi(\eta^2 y_2 + \eta y + \eta^0 y_0) \right]_{\eta=0} \quad (42)$$

$\Rightarrow A_2 = y_2 \varphi'(y_0) + \frac{y_1^2}{2!} \varphi''(y_0)$, when $\rho = 3$ we get:

$$A_3 = \frac{1}{3!} \left[\frac{d^3}{d\eta^3} \varphi \left(\sum_{i=0}^3 \eta^i y_i \right) \right]_{\eta=0} = \frac{1}{6} \left[\frac{d^3}{d\eta^3} \varphi(\eta^3 y_3 + \eta^2 y_2 + \eta y + \eta^0 y_0) \right]_{\eta=0} \quad (43)$$

$\Rightarrow A_3 = y_3 \varphi'(y_0) + y_1 y_2 \varphi''(y_0) + \frac{y_1^3}{3!} \varphi'''(y_0)$, when $\rho = 4$ we have:

$$A_4 = \frac{1}{4!} \left[\frac{d^4}{d\eta^4} \varphi \left(\sum_{i=0}^4 \eta^i y_i \right) \right]_{\eta=0} = \frac{1}{4!} \left[\frac{d^4}{d\eta^4} \varphi(\eta^4 y_4 + \eta^3 y_3 + \eta^2 y_2 + \eta y + \eta^0 y_0) \right]_{\eta=0} \quad (44)$$

$\Rightarrow A_4 = y_4 \varphi'(y_0) + \left(y_1 y_3 \varphi''(y_0) + \frac{1}{2!} y_2^2 \right) + y_1^2 y_2 \varphi'''(y_0) + \frac{y_1^4}{4!} \varphi^{iv}(y_0)$, when $\rho = 5$ we

have:

$$A_4 = \frac{1}{5!} \left[\frac{d^5}{d\eta^5} \varphi \left(\sum_{i=0}^5 \eta^i y_i \right) \right]_{\eta=0} = \frac{1}{5!} \left[\frac{d^5}{d\eta^5} \varphi(\eta^5 y_5 + \eta^4 y_4 + \eta^3 y_3 + \eta^2 y_2 + \eta y + \eta^0 y_0) \right]_{\eta=0} \quad (45)$$

$$\begin{aligned} \Rightarrow A_5 &= y_5 \varphi'(y_0) + \left(y_1 y_4 \varphi''(y_0) + y_2 y_3 \varphi''(y_0) + \frac{1}{2} y_1^2 y_3 \varphi''' \right) + \frac{1}{2} y_1 y_2^2 \varphi'''(y_0) \\ &+ \frac{1}{6} y_1^3 y_2 \varphi^{iv}(y_0) + \frac{y_1}{5!} \varphi^{iv}(y_0) \end{aligned}$$

Consider A_i , $i = 1, 2, 3, \dots$

$$A_0 = \varphi(y_0) \tag{46}$$

$$A_1 = y_1 \varphi'(y_0) \tag{47}$$

$$A_2 = y_2 \varphi'(y_0) + \frac{y^2}{2!} \varphi''(y_0) \tag{48}$$

$$A_3 = y_3 \varphi'(y_0) + y_1 y_2 \varphi''(y_0) + \frac{y^3}{3!} \varphi'''(y_0) \tag{49}$$

$$A_4 = y_4 \varphi'(y_0) + \left(y_1 y_3 \varphi''(y_0) + \frac{1}{2!} y_2^2 \right) + y_1^2 y_2 \varphi'''(y_0) + \frac{y^4}{4!} \varphi^{iv}(y_0) \tag{50}$$

$$\begin{aligned} A_5 &= y_5 \varphi'(y_0) + (y_1 y_4 + y_2 y_3) \varphi''(y_0) + \left(\frac{1}{2} y_1^2 y_3 + \frac{1}{2} y_2^2 y_1 \right) \varphi'''(y_0) + \\ &\frac{1}{6} y_1^3 y_2 \varphi^{iv}(y_0) + \frac{y_1}{5!} \varphi^{iv}(y_0) \end{aligned} \tag{51}$$

Chapter 3

APPLICATIONS

This chapter is the heart of this thesis work where we considered the application of Adomian's Decomposition Method (ADM) to four different Fractional multi-order differential equations of linear and non-linear type. The results and other analysis were discussed in Chapter 4.

3.1 Solutions of Some Examples

The first three examples considered in this section are linear multi-order fractional differential equations, while the last example has a non-linear term.

3.1.1 Example 1

Consider the following Initial value problem:

$$\frac{d^{\hat{\omega}} y}{dt^{\hat{\omega}}} + \omega^{\hat{\omega}-\bar{\sigma}} \frac{d^{\bar{\sigma}} y}{dt^{\bar{\sigma}}} = 0 \quad (52)$$

with the incipient conditions:

$$\omega = 1, y(0) = 0, y'(0) = 1. \quad (53)$$

Applying $j^{\hat{\omega}}$ on equation (52) we have:

$$y(t) - \sum_{i=0}^{m-1} y^{(i)}(0^+) \frac{t^i}{i!} + j^{\hat{\omega}} \left[\omega^{\hat{\omega}-\bar{\sigma}} \frac{d^{\bar{\sigma}} y}{dt^{\bar{\sigma}}} \right] = 0 \quad (54)$$

$$y(t) - \sum_{i=0}^{m-1} y^{(i)}(0^+) \frac{t^i}{i!} + \omega^{\hat{\omega}-\bar{\sigma}} j^{\hat{\omega}-\bar{\sigma}} \sum_{i=0}^{m-1} y_i(t) = 0 \quad (55)$$

$$y(t) - y(0) - y'(0)t + \omega^{\hat{\omega}-\bar{\sigma}} j^{\hat{\omega}-\bar{\sigma}} y(t) + \omega^{\hat{\omega}-\bar{\sigma}} j^{\hat{\omega}-\bar{\sigma}} y(0) = 0 \quad (56)$$

$$y(t) - y(0) - y'(0)t + \omega^{\hat{\sigma}-\bar{\sigma}} j^{\hat{\sigma}-\bar{\sigma}} y(t) + \omega^{\hat{\sigma}-\bar{\sigma}} j^{\hat{\sigma}-\bar{\sigma}} y(0) = 0 \quad (57)$$

$$y(t) = y(0) + y'(0)t - \omega^{\hat{\sigma}-\bar{\sigma}} j^{\hat{\sigma}-\bar{\sigma}} y(t) - \omega^{\hat{\sigma}-\bar{\sigma}} j^{\hat{\sigma}-\bar{\sigma}} y(0) \quad (58)$$

where y_0 is defined as:

$$\sum_{i=0}^{m-1} y^{(i)}(0^+) \frac{t^i}{i!} + j^{\hat{\sigma}} g(t) \quad (59)$$

given $y_0(t)$ as :

$$y(t) = y(0) + y'(0)t - \omega^{\hat{\sigma}-\bar{\sigma}} j^{\hat{\sigma}-\bar{\sigma}} y(0). \quad (60)$$

Using the initial conditions, we have: $y_0(t) = t$

$$y_{i+1}(t) = -\omega^{\hat{\sigma}-\bar{\sigma}} j^{\hat{\sigma}-\bar{\sigma}} y_i(t) \quad (61)$$

when $i = 0$, it follows that

$$y_1 = -\omega^{\hat{\sigma}-\bar{\sigma}} j^{\hat{\sigma}-\bar{\sigma}} y_0(t) \quad (62)$$

$$y_1 = -\omega^{\hat{\sigma}-\bar{\sigma}} j^{\hat{\sigma}-\bar{\sigma}} t. \quad (63)$$

Using Caputo Integral Operator, we have:

$$-\omega^{\hat{\sigma}-\bar{\sigma}} \left[\frac{1}{\Gamma(\hat{\sigma}-\bar{\sigma})} \int_0^x (x-t)^{\hat{\sigma}-\bar{\sigma}-1} t dt \right] \quad \hat{\sigma} > 0, \quad x > 0$$

$$y_1 = -\omega^{\hat{\sigma}-\bar{\sigma}} \left[\frac{1}{\Gamma(\hat{\sigma}-\bar{\sigma})} \int_0^x (x-t)^{\hat{\sigma}-\bar{\sigma}-1} t dt \right] \quad (64)$$

$$= -\omega^{\hat{\sigma}-\bar{\sigma}} \left[\frac{1}{\Gamma(\hat{\sigma}-\bar{\sigma})} \int_0^x \left(1 - \frac{t}{x}\right)^{\hat{\sigma}-\bar{\sigma}-1} x^{\hat{\sigma}-\bar{\sigma}-1} t dt \right]. \quad (65)$$

Let $a = \frac{t}{x}$, $dt = x da$, $t = ax$ when $t = 0$, $a = 0$ when $t = x$, $a = 1$

We have:

$$-\omega^{\hat{\sigma}-\check{\sigma}} \left[\frac{1}{\Gamma(\hat{\sigma}-\check{\sigma})} \int_0^1 (1-a)^{\hat{\sigma}-\check{\sigma}-1} x^{\hat{\sigma}-\check{\sigma}-1} a x^2 da \right] \quad (66)$$

$$-\omega^{\hat{\sigma}-\check{\sigma}} \left[\frac{x^{\hat{\sigma}-\check{\sigma}+1}}{\Gamma(\hat{\sigma}-\check{\sigma})} \int_0^1 (1-a)^{\hat{\sigma}-\check{\sigma}-1} a da \right] \quad (67)$$

$$-\omega^{\hat{\sigma}-\check{\sigma}} \left[\frac{x^{\hat{\sigma}-\check{\sigma}+1}}{\Gamma(\hat{\sigma}-\check{\sigma})} \frac{\Gamma(\hat{\sigma}-\check{\sigma})\Gamma(2)}{\Gamma(\hat{\sigma}-\check{\sigma}+2)} \right]. \quad (68)$$

Therefore let $t = x$ we have y_1 given below as:

$$\frac{-\omega^{\hat{\sigma}-\check{\sigma}} t^{\hat{\sigma}-\check{\sigma}+1}}{\Gamma(\hat{\sigma}-\check{\sigma}+2)} \quad (69)$$

when $i = 1$

$$y_2 = -\omega^{\hat{\sigma}-\check{\sigma}} j^{\hat{\sigma}-\check{\sigma}} y_1 t \quad (70)$$

$$y_2 = -\omega^{\hat{\sigma}-\check{\sigma}} j^{\hat{\sigma}-\check{\sigma}} \left[\frac{-\omega^{\hat{\sigma}-\check{\sigma}} t^{\hat{\sigma}-\check{\sigma}+1}}{\Gamma(\hat{\sigma}-\check{\sigma}+2)} \right]. \quad (71)$$

Using Caputo Integral Operator we have:

$$-\omega^{\hat{\sigma}-\check{\sigma}} \left[\frac{1}{\Gamma(\hat{\sigma}-\check{\sigma})} \int_0^x (x-t)^{\hat{\sigma}-\check{\sigma}-1} \left[\frac{-\omega^{\hat{\sigma}-\check{\sigma}} t^{\hat{\sigma}-\check{\sigma}+1}}{\Gamma(\hat{\sigma}-\check{\sigma}+2)} \right] dt \right] \quad \hat{\sigma} > 0, \quad x > 0$$

$$y_2 = -\omega^{\hat{\sigma}-\check{\sigma}} \left[\frac{1}{\Gamma(\hat{\sigma}-\check{\sigma})} \int_0^x (x-t)^{\hat{\sigma}-\check{\sigma}-1} \left[\frac{-\omega^{\hat{\sigma}-\check{\sigma}} t^{\hat{\sigma}-\check{\sigma}+1}}{\Gamma(\hat{\sigma}-\check{\sigma}+2)} \right] dt \right] \quad (72)$$

$$= \frac{\omega^{2(\hat{\sigma}-\check{\sigma})}}{\Gamma(\hat{\sigma}-\check{\sigma})\Gamma(\hat{\sigma}-\check{\sigma}+2)} \int_0^x (x-t)^{\hat{\sigma}-\check{\sigma}-1} t^{\hat{\sigma}-\check{\sigma}+1} dt \quad (73)$$

$$= \frac{\omega^{2(\hat{\sigma}-\check{\sigma})}}{\Gamma(\hat{\sigma}-\check{\sigma})\Gamma(\hat{\sigma}-\check{\sigma}+2)} \int_0^x \left(1 - \frac{t}{x}\right)^{\hat{\sigma}-\check{\sigma}-1} x^{\hat{\sigma}-\check{\sigma}-1} t^{\hat{\sigma}-\check{\sigma}+1} dt. \quad (74)$$

Let $a = \frac{t}{x}$, $dt = xda$, $t = ax$ when $t = 0$, $a = 0$ when $t = x$, $a = 1$

we have:

$$\frac{\omega^{2(\hat{\sigma}-\check{\sigma})}}{\Gamma(\hat{\sigma}-\check{\sigma})\Gamma(\hat{\sigma}-\check{\sigma}+2)} \int_0^1 (1-a)^{\hat{\sigma}-\check{\sigma}-1} x^{\hat{\sigma}-\check{\sigma}-1} a^{\hat{\sigma}-\check{\sigma}+1} x^{\hat{\sigma}-\check{\sigma}+1} x da \quad (75)$$

$$\frac{\omega^{2(\hat{\sigma}-\check{\sigma})}}{\Gamma(\hat{\sigma}-\check{\sigma})\Gamma(\hat{\sigma}-\check{\sigma}+2)} \int_0^1 (1-a)^{\hat{\sigma}-\check{\sigma}-1} x^{2(\hat{\sigma}-\check{\sigma})+1} a^{\hat{\sigma}-\check{\sigma}+1} da \quad (76)$$

$$\frac{\omega^{2(\hat{\sigma}-\check{\sigma})} x^{2(\hat{\sigma}-\check{\sigma})+1}}{\Gamma(\hat{\sigma}-\check{\sigma})\Gamma(\hat{\sigma}-\check{\sigma}+2)} \int_0^1 (1-a)^{\hat{\sigma}-\check{\sigma}-1} a^{\hat{\sigma}-\check{\sigma}+1} da \quad (77)$$

$$\frac{\omega^{2(\hat{\sigma}-\check{\sigma})} x^{2(\hat{\sigma}-\check{\sigma})+1}}{\Gamma(\hat{\sigma}-\check{\sigma})\Gamma(\hat{\sigma}-\check{\sigma}+2)} \frac{\Gamma(\hat{\sigma}-\check{\sigma})\Gamma(\hat{\sigma}-\check{\sigma}+2)}{\Gamma(2(\hat{\sigma}-\check{\sigma})+2)}. \quad (78)$$

Therefore let $t = x$ we have y_2 given below as:

$$y_2 = \frac{\omega^{2(\hat{\sigma}-\check{\sigma})} t^{2(\hat{\sigma}-\check{\sigma})+1}}{\Gamma(2(\hat{\sigma}-\check{\sigma})+2)} \quad (79)$$

when $i = 2$:

$$y_3 = -\omega^{\hat{\sigma}-\check{\sigma}} j^{\hat{\sigma}-\check{\sigma}} y_2 t \quad (80)$$

$$y_3 = -\omega^{\hat{\sigma}-\check{\sigma}} j^{\hat{\sigma}-\check{\sigma}} \frac{-\omega^{2(\hat{\sigma}-\check{\sigma})} t^{2(\hat{\sigma}-\check{\sigma})+1}}{\Gamma(2(\hat{\sigma}-\check{\sigma})+2)}. \quad (81)$$

Using Caputo Integral Operator we have:

$$\begin{aligned} & -\omega^{\hat{\sigma}-\check{\sigma}} \left[\frac{1}{\Gamma(\hat{\sigma}-\check{\sigma})} \int_0^x (x-t)^{\hat{\sigma}-\check{\sigma}-1} \left[\frac{-\omega^{2(\hat{\sigma}-\check{\sigma})} t^{2(\hat{\sigma}-\check{\sigma})+1}}{\Gamma(2(\hat{\sigma}-\check{\sigma})+2)} \right] dt \right] \check{\sigma} > 0, x > 0 \\ & = \frac{-\omega^{3(\hat{\sigma}-\check{\sigma})}}{\Gamma(\hat{\sigma}-\check{\sigma})\Gamma(\hat{\sigma}-\check{\sigma}+2)} \int_0^x (x-t)^{\hat{\sigma}-\check{\sigma}-1} t^{2(\hat{\sigma}-\check{\sigma})+1} dt \end{aligned} \quad (82)$$

$$= \frac{-\omega^{3(\hat{\delta}-\check{\sigma})}}{\Gamma(\hat{\delta}-\check{\sigma})\Gamma(2(\hat{\delta}-\check{\sigma})+2)} \int_0^x \left(1-\frac{t}{x}\right)^{\hat{\delta}-\check{\sigma}-1} x^{\hat{\delta}-\check{\sigma}-1} t^{2(\hat{\delta}-\check{\sigma})+1} dt. \quad (83)$$

Let $a = \frac{t}{x}$, $dt = xda$, $t = ax$ when $t=0$, $a=0$ when $t=x$, $a=1$

we have:

$$= \frac{-\omega^{3(\hat{\delta}-\check{\sigma})}}{\Gamma(\hat{\delta}-\check{\sigma})\Gamma(2(\hat{\delta}-\check{\sigma})+2)} \int_0^1 (1-a)^{\hat{\delta}-\check{\sigma}-1} x^{\hat{\delta}-\check{\sigma}-1} ax^{2(\hat{\delta}-\check{\sigma})+1} x da \quad (84)$$

$$= \frac{-\omega^{3(\hat{\delta}-\check{\sigma})}}{\Gamma(\hat{\delta}-\check{\sigma})\Gamma(2(\hat{\delta}-\check{\sigma})+2)} \int_0^1 (1-a)^{\hat{\delta}-\check{\sigma}-1} x^{3(\hat{\delta}-\check{\sigma})+1} a^{2(\hat{\delta}-\check{\sigma})+1} da \quad (85)$$

$$= \frac{-\omega^{3(\hat{\delta}-\check{\sigma})} x^{3(\hat{\delta}-\check{\sigma})+1}}{\Gamma(\hat{\delta}-\check{\sigma})\Gamma(2(\hat{\delta}-\check{\sigma})+2)} \frac{\Gamma(\hat{\delta}-\check{\sigma})\Gamma(2(\hat{\delta}-\check{\sigma})+2)}{\Gamma(3(\hat{\delta}-\check{\sigma})+2)}. \quad (86)$$

Let $t = x$ we get y_3 as given below:

$$y_3 = \frac{-\omega^{3(\hat{\delta}-\check{\sigma})} x^{3(\hat{\delta}-\check{\sigma})+1}}{\Gamma(3(\hat{\delta}-\check{\sigma})+2)} \quad (87)$$

When $i = 3$,

$$y_4 = -\omega^{\hat{\delta}-\check{\sigma}} j^{\hat{\delta}-\check{\sigma}} y_3 t \quad (88)$$

$$y_4 = -\omega^{\hat{\delta}-\check{\sigma}} j^{\hat{\delta}-\check{\sigma}} \frac{-\omega^{3(\hat{\delta}-\check{\sigma})} x^{3(\hat{\delta}-\check{\sigma})+1}}{\Gamma(3(\hat{\delta}-\check{\sigma})+2)}. \quad (89)$$

Using Caputo Integral Operator, we have:

$$-\omega^{\hat{\delta}-\check{\sigma}} \left[\frac{1}{\Gamma(\hat{\delta}-\check{\sigma})} \int_0^x (x-t)^{\hat{\delta}-\check{\sigma}-1} \left[\frac{-\omega^{3(\hat{\delta}-\check{\sigma})} t^{3(\hat{\delta}-\check{\sigma})+1}}{\Gamma(3(\hat{\delta}-\check{\sigma})+2)} \right] dt \right] \check{\sigma} > 0, x > 0$$

$$y_4 = \frac{-\omega^{4(\hat{\delta}-\check{\sigma})}}{\Gamma(\hat{\delta}-\check{\sigma})\Gamma(3(\hat{\delta}-\check{\sigma})+2)} \int_0^x (x-t)^{\hat{\delta}-\check{\sigma}-1} t^{3(\hat{\delta}-\check{\sigma})+1} dt \quad (90)$$

$$y_4 = \frac{-\omega^{4(\hat{\delta}-\check{\sigma})}}{\Gamma(\hat{\delta}-\check{\sigma})\Gamma(3(\hat{\delta}-\check{\sigma})+2)} \int_0^x \left(1-\frac{t}{x}\right)^{\hat{\delta}-\check{\sigma}-1} x^{\hat{\delta}-\check{\sigma}-1} t^{3(\hat{\delta}-\check{\sigma})+1} dt. \quad (91)$$

Let $a = \frac{t}{x}$, $dt = xda$, $t = ax$ when $t=0$, $a=0$ when $t=x$, $a=1$

Therefore we have:

$$y_4 = \frac{\omega^{4(\hat{\delta}-\check{\sigma})}}{\Gamma(\hat{\delta}-\check{\sigma})\Gamma(3(\hat{\delta}-\check{\sigma})+2)} \int_0^1 (1-a)^{\hat{\delta}-\check{\sigma}-1} x^{\hat{\delta}-\check{\sigma}-1} a x^{3(\hat{\delta}-\check{\sigma})+1} x da \quad (92)$$

$$y_4 = \frac{\omega^{4(\hat{\delta}-\check{\sigma})}}{\Gamma(\hat{\delta}-\check{\sigma})\Gamma(3(\hat{\delta}-\check{\sigma})+2)} \int_0^1 (1-a)^{\hat{\delta}-\check{\sigma}-1} x^{4(\hat{\delta}-\check{\sigma})+1} a^{3(\hat{\delta}-\check{\sigma})+1} da \quad (93)$$

$$= \frac{\omega^{4(\hat{\delta}-\check{\sigma})} x^{4(\hat{\delta}-\check{\sigma})+1}}{\Gamma(\hat{\delta}-\check{\sigma})\Gamma(3(\hat{\delta}-\check{\sigma})+2)} \frac{\Gamma(\hat{\delta}-\check{\sigma})\Gamma(3(\hat{\delta}-\check{\sigma})+2)}{\Gamma(4(\hat{\delta}-\check{\sigma})+2)}. \quad (94)$$

Therefore let $t = x$ we have y_4 as given below:

$$y_4 = \frac{\omega^{4(\hat{\delta}-\check{\sigma})} x^{4(\hat{\delta}-\check{\sigma})+1}}{\Gamma(4(\hat{\delta}-\check{\sigma})+2)} \quad (95)$$

with the recursive relativity, the terms of the decomposition series are:

$$y_1 = \frac{-\omega^{(\hat{\delta}-\check{\sigma})} t^{(\hat{\delta}-\check{\sigma})+1}}{\Gamma((\hat{\delta}-\check{\sigma})+2)} \quad (96)$$

$$y_2 = \frac{\omega^{2(\hat{\delta}-\check{\sigma})} t^{2(\hat{\delta}-\check{\sigma})+1}}{\Gamma(2(\hat{\delta}-\check{\sigma})+2)} \quad (97)$$

$$y_3 = \frac{\omega^{3(\hat{\delta}-\check{\sigma})} t^{3(\hat{\delta}-\check{\sigma})+1}}{\Gamma(3(\hat{\delta}-\check{\sigma})+2)} \quad (98)$$

$$y_4 = \frac{\omega^{4(\hat{\delta}-\check{\sigma})} t^{4(\hat{\delta}-\check{\sigma})+1}}{\Gamma(4(\hat{\delta}-\check{\sigma})+2)} \quad (99)$$

Substituting $y_0, y_1, y_2, y_3, y_4, \dots$ into equation (38) we have:

$$y(t) = \frac{-\omega^{(\hat{\sigma}-\check{\sigma})} t^{(\hat{\sigma}-\check{\sigma})+1}}{\Gamma((\hat{\sigma}-\check{\sigma})+2)} + \frac{\omega^{2(\hat{\sigma}-\check{\sigma})} t^{2(\hat{\sigma}-\check{\sigma})+1}}{\Gamma(2(\hat{\sigma}-\check{\sigma})+2)} - \frac{\omega^{3(\hat{\sigma}-\check{\sigma})} t^{3(\hat{\sigma}-\check{\sigma})+1}}{\Gamma(3(\hat{\sigma}-\check{\sigma})+2)} + \frac{\omega^{4(\hat{\sigma}-\check{\sigma})} t^{4(\hat{\sigma}-\check{\sigma})+1}}{\Gamma(4(\hat{\sigma}-\check{\sigma})+2)} - \dots \quad (100)$$

The series model of the solution is given as:

$$y(t) = \sum (-1)^i \omega^{i(\hat{\sigma}-\check{\sigma})} \frac{t^{i(\hat{\sigma}-\check{\sigma})+1}}{\Gamma(i(\hat{\sigma}-\check{\sigma})+2)} \quad (101)$$

Let $\hat{\sigma} = 2$, and $\check{\sigma} = 0$ we have:

$$y(t) = \frac{1}{\Gamma(2)} - \frac{\omega^2 t^3}{\Gamma(4)} + \frac{\omega^4 t^5}{\Gamma(6)} - \frac{\omega^6 t^7}{\Gamma(8)} + \dots \quad (102)$$

Which is simple harmonic oscillator's solution expressed further as:

$$y(t) = \frac{1}{\omega} \sin(\omega t) \quad (103)$$

which mean the frictional force is zero and the motion is periodic. Since it is a simple harmonic oscillator it has a constant total energy. The plane phase blue print is always closed curve (ellipse) for various values of v and x , it is periodic because it moves in clock-wise direction.

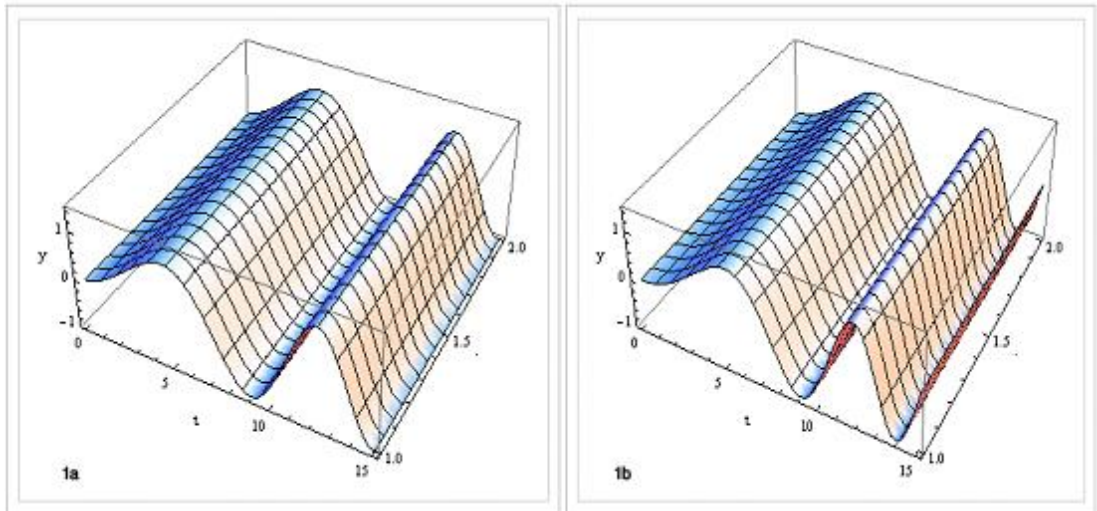


Figure 1. Solution of Example 1

Figure 1a is the solution of example 1 when $1 < \hat{\delta} \leq 2$, and $\check{\sigma} = 0$ while Figure 1b is also a display of the solution of example 1 when $0 < \check{\sigma} \leq 1$ and $\hat{\delta} = 0$ respectively.

It was observed that when we set $\check{\sigma} = 0$ and vary $\hat{\delta}$ there was an increase in frequency with increase in the values of $\hat{\delta}$ within the interval $1 < \hat{\delta} \leq 2$ as display in Figure 1a above. Similarly when we set $\hat{\delta} = 2$, and vary $\check{\sigma}$ we discovered that the frequency decrease with decreases in the values $\check{\sigma}$ within the interval $0 < \check{\sigma} \leq 1$ as display in Figure 1b above. It is clear that our results for the two cases considered is in agreement with the solution obtained in other literatures using other various methods [1] .

3.1.2 Example 2

Consider the Initial value problem:

$$\frac{d^{\hat{\delta}} y}{dt^{\hat{\delta}}} - k \frac{d^{\check{\sigma}} y}{dt^{\check{\sigma}}} = 0 \quad (104)$$

equation(104) depends on the incipient conditions:

$$k = 1, y'(0) = 1, y(0) = 0. \quad (105)$$

Applying $j^{\hat{\delta}}$ to equation(104) we have:

$$y(t) - \sum_{n=0}^{m-1} y^{(n)}(0^+) \frac{t^n}{n!} - j^{\hat{\delta}} \left[k \frac{d^{\check{\sigma}} y}{dt^{\check{\sigma}}} \right] = 0 \quad (106)$$

$$y(t) - \sum_{n=0}^{m-1} y^{(n)}(0^+) \frac{t^n}{n!} - k j^{\hat{\delta}-\check{\sigma}} \sum_{n=0}^{m-1} y_n(t) = 0 \quad (107)$$

$$y(t) - y(0) - y'(0)t - k j^{\hat{\delta}-\check{\sigma}} y(t) - k j^{\hat{\delta}-\check{\sigma}} y(0) = 0 \quad (108)$$

where y_0 is defined as :

$$\sum_{n=0}^{m-1} y^{(n)}(0^+) \frac{t^n}{n!} + j^{\hat{\sigma}} g(t). \quad (109)$$

Then,

$$y(t) = y(0) + y'(0)t + kj^{\hat{\sigma}-\bar{\sigma}} y(t) + kj^{\hat{\sigma}-\bar{\sigma}} y(0) \quad (110)$$

where

$$y_0(t) = y(0) + y'(0)t + kj^{\hat{\sigma}-\bar{\sigma}} y(0). \quad (111)$$

Considering the equation(105)

$$y_0(t) = t \quad (112)$$

and

$$y_{n+1}(t) = kj^{\hat{\sigma}-\bar{\sigma}} y_n(t) \quad (113)$$

when $n=(0)$,

$$y_1(t) = kj^{\hat{\sigma}-\bar{\sigma}} y_0(t) \quad (114)$$

$$y_1(t) = kj^{\hat{\sigma}-\bar{\sigma}} t. \quad (115)$$

Using Caputo Integral Operator we have:

$$k \left[\frac{1}{\Gamma(\hat{\sigma}-\bar{\sigma})} \int_0^x (x-t)^{\hat{\sigma}-\bar{\sigma}-1} t dt \right], \hat{\sigma} > 0, x > 0$$

$$y_1 = k \left[\frac{1}{\Gamma(\hat{\sigma}-\bar{\sigma})} \int_0^x (x-t)^{\hat{\sigma}-\bar{\sigma}-1} t dt \right], \hat{\sigma} > 0, x > 0 \quad (116)$$

$$= k \left[\frac{1}{\Gamma(\hat{\sigma}-\bar{\sigma})} \int_0^x \left(1 - \frac{t}{x}\right)^{\hat{\sigma}-\bar{\sigma}-1} x^{(\hat{\sigma}-\bar{\sigma}-1)} t dt \right], \hat{\sigma} > 0, x > 0. \quad (117)$$

Let $a = \frac{t}{x}$, $dt = xda$, $t = ax$ when $t = 0$, $a = 0$ when $t = x$, $a = 1$

we have:

$$k \left[\frac{1}{\Gamma(\hat{\sigma} - \check{\sigma})} \int_0^x (1-a)^{\hat{\sigma} - \check{\sigma} - 1} x^{(\hat{\sigma} - \check{\sigma} - 1)} ax^2 da \right] \quad (118)$$

$$k \left[\frac{x^{(\hat{\sigma} - \check{\sigma} + 1)}}{\Gamma(\hat{\sigma} - \check{\sigma})} \int_0^x (1-a)^{\hat{\sigma} - \check{\sigma} - 1} ada \right] \quad (119)$$

$$k \left[\frac{x^{(\hat{\sigma} - \check{\sigma} + 1)} \Gamma(\hat{\sigma} - \check{\sigma}) \Gamma(2)}{\Gamma(\hat{\sigma} - \check{\sigma}) \Gamma(\hat{\sigma} - \check{\sigma} + 2)} \right]. \quad (120)$$

Therefore let $t = x$ we have y_1 as given below as:

$$\left[\frac{kt^{(\hat{\sigma} - \check{\sigma} + 1)}}{\Gamma(\hat{\sigma} - \check{\sigma} + 2)} \right] \quad (121)$$

when $n = 1$

$$y_2(t) = kj^{\hat{\sigma} - \check{\sigma}} y_1(t) \quad (122)$$

$$y_2(t) = kj^{\hat{\sigma} - \check{\sigma}} \left[\frac{kt^{(\hat{\sigma} - \check{\sigma} + 1)}}{\Gamma(\hat{\sigma} - \check{\sigma} + 2)} \right]. \quad (123)$$

Using Caputo Integral Operator we have:

$$k \left[\frac{1}{\Gamma(\hat{\sigma} - \check{\sigma})} \int_0^x (x-t)^{\hat{\sigma} - \check{\sigma} - 1} \left[\frac{kt^{(\hat{\sigma} - \check{\sigma} + 1)}}{\Gamma(\hat{\sigma} - \check{\sigma} + 2)} \right] dt \right], \hat{\sigma} > 0, x > 0$$

$$y_2 = k \left[\frac{1}{\Gamma(\hat{\sigma} - \check{\sigma})} \int_0^x (x-t)^{\hat{\sigma} - \check{\sigma} - 1} \left[\frac{kt^{(\hat{\sigma} - \check{\sigma} + 1)}}{\Gamma(\hat{\sigma} - \check{\sigma} + 2)} \right] dt \right] \quad (124)$$

$$= \left[\frac{k^2}{\Gamma(\hat{\sigma} - \check{\sigma}) \Gamma(\hat{\sigma} - \check{\sigma} + 2)} \int_0^x (x-t)^{\hat{\sigma} - \check{\sigma} - 1} t^{\hat{\sigma} - \check{\sigma} + 1} dt \right] \quad (125)$$

$$= \left[\frac{k^2}{\Gamma(\hat{\sigma}-\bar{\sigma})\Gamma(\hat{\sigma}-\bar{\sigma}+2)} \int_0^x \left(1-\frac{t}{x}\right)^{\hat{\sigma}-\bar{\sigma}-1} x^{\hat{\sigma}-\bar{\sigma}-1} t^{\hat{\sigma}-\bar{\sigma}+1} dt \right]. \quad (126)$$

Let $a = \frac{t}{x}$, $dt = xda$, $t = ax$ when $t=0$, $a=0$ when $t=x$, $a=1$

we have:

$$\left[\frac{k^2}{\Gamma(\hat{\sigma}-\bar{\sigma})\Gamma(\hat{\sigma}-\bar{\sigma}+2)} \int_0^1 (1-a)^{\hat{\sigma}-\bar{\sigma}-1} x^{\hat{\sigma}-\bar{\sigma}-1} a^{\hat{\sigma}-\bar{\sigma}+1} x^{\hat{\sigma}-\bar{\sigma}+1} x da \right] \quad (127)$$

$$\left[\frac{k^2}{\Gamma(\hat{\sigma}-\bar{\sigma})\Gamma(\hat{\sigma}-\bar{\sigma}+2)} \int_0^1 (1-a)^{\hat{\sigma}-\bar{\sigma}-1} x^{2(\hat{\sigma}-\bar{\sigma})+1} a^{\hat{\sigma}-\bar{\sigma}+1} da \right] \quad (128)$$

$$\left[\frac{k^2 x^{2(\hat{\sigma}-\bar{\sigma})+1}}{\Gamma(\hat{\sigma}-\bar{\sigma})\Gamma(\hat{\sigma}-\bar{\sigma}+2)} \int_0^1 (1-a)^{\hat{\sigma}-\bar{\sigma}-1} a^{\hat{\sigma}-\bar{\sigma}+1} da \right] \quad (129)$$

$$\frac{k^2 x^{2(\hat{\sigma}-\bar{\sigma})+1}}{\Gamma(\hat{\sigma}-\bar{\sigma})\Gamma(\hat{\sigma}-\bar{\sigma}+2)} \frac{\Gamma(\hat{\sigma}-\bar{\sigma})\Gamma(\hat{\sigma}-\bar{\sigma}+2)}{\Gamma(2(\hat{\sigma}-\bar{\sigma})+2)}. \quad (130)$$

Therefore let $t = x$ we have y_2 as given below:

$$y_2 = \frac{k^2 x^{2(\hat{\sigma}-\bar{\sigma})+1}}{\Gamma(2(\hat{\sigma}-\bar{\sigma})+2)} \quad (131)$$

when $n = 2$,

$$y_3(t) = kj^{\hat{\sigma}-\bar{\sigma}} y_2(t) \quad (132)$$

then

$$y_3(t) = kj^{\hat{\sigma}-\bar{\sigma}} \frac{k^2 x^{2(\hat{\sigma}-\bar{\sigma})+1}}{\Gamma(2(\hat{\sigma}-\bar{\sigma})+2)}. \quad (133)$$

Using Caputo Integral Operator we have:

$$k \left[\frac{1}{\Gamma(\hat{\delta}-\bar{\sigma})} \int_0^x (x-t)^{\hat{\delta}-\bar{\sigma}-1} \left[\frac{k^2 x^{2(\hat{\delta}-\bar{\sigma})+1}}{\Gamma(2(\hat{\delta}-\bar{\sigma})+2)} \right] dt \right], \hat{\delta} > 0, x > 0$$

$$y_3 = \left[\frac{k^3}{\Gamma(\hat{\delta}-\bar{\sigma})\Gamma(2(\hat{\delta}-\bar{\sigma})+2)} \int_0^x (x-t)^{\hat{\delta}-\bar{\sigma}-1} t^{2(\hat{\delta}-\bar{\sigma})+1} dt \right] \quad (134)$$

$$= \left[\frac{k^3}{\Gamma(\hat{\delta}-\bar{\sigma})\Gamma(2(\hat{\delta}-\bar{\sigma})+2)} \int_0^x \left(1-\frac{t}{x}\right)^{\hat{\delta}-\bar{\sigma}-1} x^{\hat{\delta}-\bar{\sigma}-1} t^{2(\hat{\delta}-\bar{\sigma})+1} dt \right]. \quad (135)$$

Let $a = \frac{t}{x}$, $dt = x da$, $t = ax$ when $t = 0$, $a = 0$ when $t = x$, $a = 1$

we have:

$$\left[\frac{k^3}{\Gamma(\hat{\delta}-\bar{\sigma})\Gamma(2(\hat{\delta}-\bar{\sigma})+2)} \int_0^1 (1-a)^{\hat{\delta}-\bar{\sigma}-1} x^{\hat{\delta}-\bar{\sigma}-1} a x^{2(\hat{\delta}-\bar{\sigma})+1} x da \right] \quad (136)$$

$$\left[\frac{k^3}{\Gamma(\hat{\delta}-\bar{\sigma})\Gamma(2(\hat{\delta}-\bar{\sigma})+2)} \int_0^1 (1-a)^{\hat{\delta}-\bar{\sigma}-1} x^{3(\hat{\delta}-\bar{\sigma})+1} a^{2(\hat{\delta}-\bar{\sigma})+1} da \right] \quad (137)$$

$$\left[\frac{k^3 x^{3(\hat{\delta}-\bar{\sigma})+1}}{\Gamma(\hat{\delta}-\bar{\sigma})\Gamma(2(\hat{\delta}-\bar{\sigma})+2)} \frac{\Gamma(\hat{\delta}-\bar{\sigma})\Gamma(2(\hat{\delta}-\bar{\sigma})+2)}{\Gamma(3(\hat{\delta}-\bar{\sigma})+2)} \right] \quad (138)$$

Therefore let $t = x$ we have y_3 as given below:

$$y_3 = \frac{k^3 t^{3(\hat{\delta}-\bar{\sigma})+1}}{\Gamma(3(\hat{\delta}-\bar{\sigma})+2)}. \quad (139)$$

With the recursive relativity, the terms of the decomposition series are given below:

$$y(t) = \frac{kt^{(\hat{\delta}-\bar{\sigma})+1}}{\Gamma((\hat{\delta}-\bar{\sigma})+2)} + \frac{k^2 t^{2(\hat{\delta}-\bar{\sigma})+1}}{\Gamma(2(\hat{\delta}-\bar{\sigma})+2)} + \frac{k^3 t^{3(\hat{\delta}-\bar{\sigma})+1}}{\Gamma(3(\hat{\delta}-\bar{\sigma})+2)} + \dots \quad (140)$$

The series model of the solution is given as:

$$y(t) = \sum_{n=0}^{\infty} \frac{k^n t^{n(\hat{\sigma}-\check{\sigma})+1}}{\Gamma(n(\hat{\sigma}-\check{\sigma})+2)} \quad (141)$$

Let $\hat{\sigma} = 1$, $\check{\sigma} = 0$ we have:

$$y(t) = \frac{t}{\Gamma(2)} + \frac{kt^2}{\Gamma(3)} + \frac{k^2t^3}{\Gamma(4)} + \dots \quad (142)$$

Which is the solution of exponential growth equation given by:

$$y(t) = y_0 e^{(kt)} \quad (143)$$

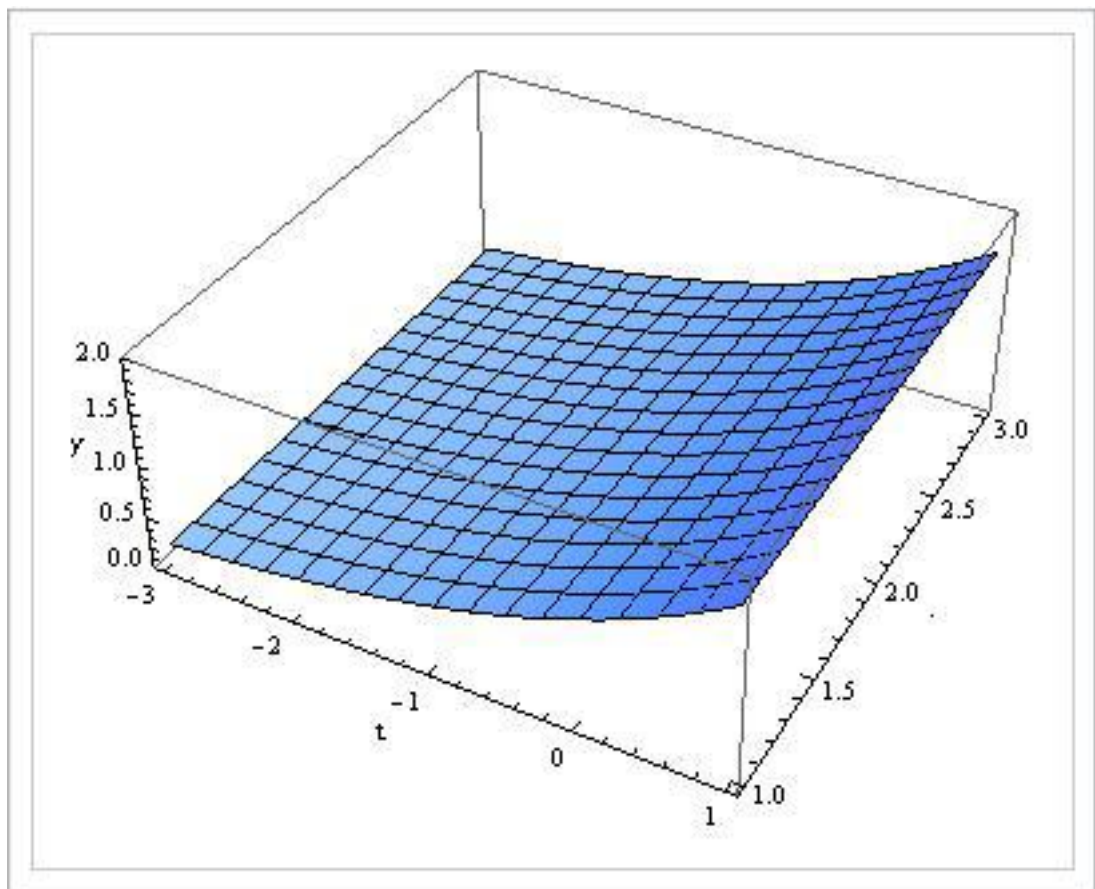


Figure 2. Solution to Example 2

If $\hat{\delta} = 1$ and $\check{\sigma} = 0$ equation (104) becomes the equation of exponential growth.

Figure represent the solution of Example 2 when $1 \leq \hat{\delta} < 2$ and $0 \leq \check{\sigma} < 1$.

3.1.3 Example 3

Consider the following I.V.P:

$$\frac{d^\alpha y}{dt^\alpha} - a \frac{d^{\beta_1} y}{dt^{\beta_1}} - b \frac{d^{\beta_2} y}{dt^{\beta_2}} = 0 \quad (144)$$

With incipient conditions:

$$y^{(i)}(0) = \rho_i, \quad i = 0, 1, 2, 3, \dots, n-1 \quad (145)$$

Applying j^α to equation (144) we have:

$$y(t) - \sum_{i=0}^{n-1} y^{(i)}(0) \frac{t^i}{i!} - j^\alpha \left[a \frac{d^{\beta_1} y}{dt^{\beta_1}} - b \frac{d^{\beta_2} y}{dt^{\beta_2}} \right] = 0 \quad (146)$$

Where:

$$\sum_{i=0}^{n-1} \frac{d^\alpha y}{dt^\alpha} = y(t) - \sum_{i=0}^{n-1} y^{(i)}(0) \frac{t^i}{i!} \quad (147)$$

The equation (144) becomes:

$$\begin{aligned} y(t) - \sum_{i=0}^{n-1} y^{(i)}(0) \frac{t^i}{i!} - a j^{\alpha-\beta_1} y(t) - a \sum_{i=0}^{n-1} y^{(i)}(0) j^{\alpha-\beta_1} \frac{t^i}{i!} - b j^{\alpha-\beta_2} y(t) \\ - b \sum_{i=0}^{n-1} y^{(i)}(0) j^{\alpha-\beta_2} \frac{t^i}{i!} = 0 \end{aligned} \quad (148)$$

Recall equation (45), we have:

$$y(t) - \sum_{i=0}^{n-1} \rho_i \frac{t^i}{i!} - a j^{\alpha-\beta_1} y(t) - a \sum_{i=0}^{l-1} \rho_i j^{\alpha-\beta_1} \frac{t^i}{i!} - b j^{\alpha-\beta_2} y(t) - \sum_{i=0}^{r-1} \rho_i j^{\alpha-\beta_2} \frac{t^i}{i!} = 0 \quad (149)$$

Where in the Caputo sense we have:

$$\sum_{i=0}^{l-1} \rho_i j^{\alpha-\beta_1} = \sum_{i=0}^{l-1} \rho_i \frac{t^{\alpha-\beta_1+i}}{\Gamma(\alpha-\beta_1+i+1)} \quad (150)$$

that is:

$$j^{\alpha-\beta_1} \frac{t^i}{i!} = \frac{1}{\Gamma(\alpha-\beta_1)} \int_0^x (x-t)^{\alpha-\beta_1-1} \frac{t^i}{i!} dt \quad (151)$$

$$j^{\alpha-\beta_1} \frac{t^i}{i!} = \frac{1}{\Gamma(\alpha-\beta_1)} \int_0^x \left(1-\frac{t}{x}\right)^{\alpha-\beta_1-1} x^{\alpha-\beta_1-1} \frac{t^i}{i!} dt \quad (152)$$

Let $u = \frac{t}{x}$, $dt = xdu$, $t = ux$ when $t=0$, $u=0$ when $t=x$, $u=1$, we have:

$$j^{\alpha-\beta_1} \frac{t^i}{i!} = \frac{1}{\Gamma(\alpha-\beta_1)} \int_0^1 (1-u)^{\alpha-\beta_1-1} x^{\alpha-\beta_1-1} \frac{u^i x^i}{i!} x du \quad (153)$$

$$j^{\alpha-\beta_1} \frac{t^i}{i!} = \frac{1}{\Gamma(\alpha-\beta_1) i!} \int_0^1 (1-u)^{\alpha-\beta_1-1} x^{\alpha-\beta_1+i} u^i x^i du \quad (154)$$

$$j^{\alpha-\beta_1} \frac{t^i}{i!} = \frac{x^{\alpha-\beta_1+i}}{\Gamma(\alpha-\beta_1) i!} \int_0^1 (1-u)^{\alpha-\beta_1-1} u^i du \quad (155)$$

$$= \frac{x^{\alpha-\beta_1+i}}{\Gamma(\alpha-\beta_1) i!} \frac{\Gamma(\alpha-\beta_1) \Gamma(i+1)}{\Gamma(\alpha-\beta_1+1+i)} \quad (156)$$

$$= \frac{x^{\alpha-\beta_1+i}}{\Gamma(\alpha-\beta_1) i! \Gamma(\alpha-\beta_1+1+i)} \quad (157)$$

$$= \frac{x^{\alpha-\beta_1+i}}{\Gamma(\alpha-\beta_1+1+i) i!} \quad (158)$$

therefore:

$$\sum_{i=0}^{l-1} \rho_i j^{\alpha-\beta_1} = \sum_{i=0}^{l-1} \rho_i \frac{t^{\alpha-\beta_1+i}}{\Gamma(\alpha-\beta_1+i+1)} \quad (159)$$

Similarly:

$$\sum_{i=0}^{r-1} \rho_i j^{\alpha-\beta_2} = \sum_{i=0}^{r-1} \rho_i \frac{x^{\alpha-\beta_2+i}}{\Gamma(\alpha-\beta_2+i+1)} \quad (160)$$

Then the equation (146) becomes:

$$\begin{aligned} y(t) - \sum_{i=0}^{n-1} \rho_i \frac{t^i}{i!} - aj^{\alpha-\beta_1} y(t) - a \sum_{i=0}^{l-1} \rho_i \frac{x^{\alpha-\beta_1+i}}{\Gamma(\alpha-\beta_1+i+1)} - bj^{\alpha-\beta_2} y(t) \\ - b \sum_{i=0}^{l-1} \rho_i \frac{x^{\alpha-\beta_2+i}}{\Gamma(\alpha-\beta_2+i+1)} = 0 \end{aligned} \quad (161)$$

Let

$$\psi_1(t) = \sum_{i=0}^{n-1} \rho_i \frac{t^i}{i!} \quad (162)$$

$$\psi_2(t) = \sum_{i=0}^{l-1} \rho_i \frac{t^{\alpha-\beta_1+i}}{\Gamma(\alpha-\beta_1+i+1)} \quad (163)$$

$$\psi_3(t) = \sum_{i=0}^{s-1} \rho_i \frac{t^{\alpha-\beta_2+i}}{\Gamma(\alpha-\beta_2+i+1)} \quad (164)$$

Then:

$$y(t) - \psi_1(t) - aj^{\alpha-\beta} y(t) - a\psi_2(t) - bj^{\alpha-\beta_2} y(t) - b\psi_3(t) = 0 \quad (165)$$

$$y(t) = \psi_1(t) + aj^{\alpha-\beta} y(t) + a\psi_2(t) + bj^{\alpha-\beta_2} y(t) + b\psi_3(t) \quad (166)$$

By rearranging:

$$y(t) = \psi_1(t) + a\psi_2(t) + b\psi_3(t) + aj^{\alpha-\beta} y(t) + bj^{\alpha-\beta_2} y(t) \quad (167)$$

Therefore the terms of $y(t)$ is determined by:

$$y_0 = \psi_1(t) + a\psi_2(t) + b\psi_3(t) \quad (168)$$

$$y_{k+1} = (aj^{\alpha-\beta}y(t) + bj^{\alpha-\beta_2}y(t))y_k(t), k \geq 1 \quad (169)$$

With the recursive relativity, the term of the decomposition series are given below:

$$y_1 = (aj^{\alpha-\beta} + bj^{\alpha-\beta_2})y_1(t) \quad (170)$$

$\forall k = 0$,

$$\Rightarrow y_1 = (aj^{\alpha-\beta} + bj^{\alpha-\beta_2})\psi_1(t) + a\psi_2(t) + b\psi_3(t) \quad (171)$$

Also when $k = 1$ we have:

$$y_2 = (aj^{\alpha-\beta} + bj^{\alpha-\beta_2})y_1(t) \quad (172)$$

$\forall k = 1$

$$\Rightarrow y_2 = (aj^{\alpha-\beta} + bj^{\alpha-\beta_2})(aj^{\alpha-\beta} + bj^{\alpha-\beta_2})\psi_1(t) + a\psi_2(t) + b\psi_3(t) \quad (173)$$

$$\Rightarrow y_2 = (aj^{\alpha-\beta} + bj^{\alpha-\beta_2})^2 \psi_1(t) + a\psi_2(t) + b\psi_3(t) \quad (174)$$

Also when $k = 2$ we have:

$$\Rightarrow y_2 = (aj^{\alpha-\beta} + bj^{\alpha-\beta_2})(aj^{\alpha-\beta} + bj^{\alpha-\beta_2})(aj^{\alpha-\beta} + bj^{\alpha-\beta_2})\psi_1(t) + a\psi_2(t) + b\psi_3(t) \quad (176)$$

$$y_3 = (aj^{\alpha-\beta} + bj^{\alpha-\beta_2})^3 \psi_1(t) + a\psi_2(t) + b\psi_3(t) \quad (177)$$

Also when $k = 3$ we have:

$$y_4 = (aj^{\alpha-\beta} + bj^{\alpha-\beta_2})y_3(t) \quad (178)$$

$\forall k = 3$,

$$y_4 = (aj^{\alpha-\beta} + bj^{\alpha-\beta_2})^4 \psi_1(t) + a\psi_2(t) + b\psi_3(t) \quad (179)$$

$$y_k = (aj^{\alpha-\beta} + bj^{\alpha-\beta_2})^k y_{k-1}(t), \forall k \quad (180)$$

$$y_k = (aj^{\alpha-\beta} + bj^{\alpha-\beta_2})^k \psi_1(t) + a\psi_2(t) + b\psi_3(t) \quad (181)$$

Expanding the operator using binomial formula a series solution is obtained:

$$y(t) = \sum_{k=0}^{\infty} \sum_{j=0}^k \binom{k}{j} a^j b^{k-j} j^{k\alpha-j\beta_1-k\beta_2+j\alpha} \psi_1(t) + a\psi_2(t) + b\psi_3(t) \quad (182)$$

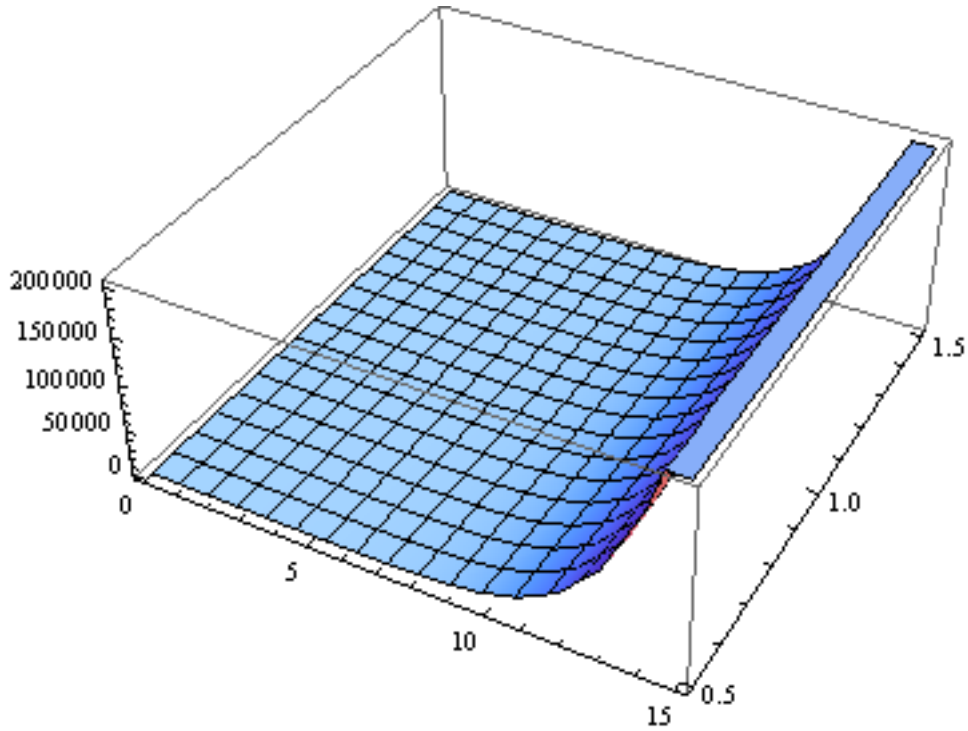


Figure 3. Solution to Example 3

The solution of Example 3 is display above for the values of $0.5 \leq \beta_1 \leq 1.5$ and

$\beta_2 = 0$ when $\alpha = 2$ $\beta_1 = \frac{3}{2}$ and $\beta_2 = 0$ in equation(144) we obtained the solution of

Bagley Torvik equation. From Figure 3 above, we discover that the amplitude increases with increase in β_1 within the interval $0.5 \leq \beta_1 \leq 1.5$. The examples

considered so far shows the efficiency of the method of solutions for three different multi-order fractional differential equations.

3.1.4 Example 4

Now consider the non-linear case:

$$\frac{d^{\hat{\phi}} y}{dt^{\hat{\phi}}} - y(t) \frac{d^{\bar{\sigma}} y}{dt^{\bar{\sigma}}} - 1 = 0 \quad 1 < \hat{\phi} \leq 2, \quad 0 \leq \bar{\sigma} < \hat{\phi} \quad (183)$$

with the incipient condition $y^i(0) = 0 \quad i = 0, 1, \dots, m-1$

Applying $j^{\hat{\phi}}$ we have:

$$j^{\hat{\phi}} \left[\frac{d^{\hat{\phi}} y}{dt^{\hat{\phi}}} - y(t) \frac{d^{\bar{\sigma}} y}{dt^{\bar{\sigma}}} - 1 \right] = 0 \quad (184)$$

From equation(17):

$$y(t) \frac{d^{\bar{\sigma}} y}{dt^{\bar{\sigma}}} = Ny(t), \quad Ny(t) = \sum_{\rho=0}^{\infty} A_{\rho} \text{ and } j^{\hat{\phi}} \left(\sum_{\rho=0}^{\infty} A_{\rho} \right) = j^{\hat{\phi}} A_{\rho} \quad (185)$$

We have:

$$j^{\hat{\phi}} \left[\frac{d^{\hat{\phi}} y}{dt^{\hat{\phi}}} - y(t) \frac{d^{\bar{\sigma}} y}{dt^{\bar{\sigma}}} - 1 \right] = 0$$

$$j^{\hat{\phi}} \frac{d^{\bar{\sigma}} y}{dt^{\bar{\sigma}}} - j^{\hat{\phi}} \sum_{k=0}^{\infty} A_{\rho} - j^{\hat{\phi}}(1) = 0 \quad (187)$$

$$y(t) - \sum_{i=0}^{n-1} y^i(0) \frac{t^i}{i!} - j^{\hat{\phi}} A_{\rho} - j^{\hat{\phi}}(1) = 0 \quad (188)$$

Applying initial condition, we have:

$$y(t) - j^{\hat{\phi}} A_{\rho} - j^{\hat{\phi}}(1) = 0 \quad (189)$$

Therefore:

$$y(t) = j^{\hat{\phi}} A_{\rho} + j^{\hat{\phi}}(1) = 0 \quad (190)$$

The terms of $y(t)$ are determined by:

$$y_0(t) = j^{\hat{\phi}}(1) \quad (191)$$

$$y_{\rho+1}(t) = j^{\hat{\phi}} A_{\rho} \quad (192)$$

The general formula for the Adomian's Polynomial will be used to calculate the non-linear function.

$$A_{\rho} = \frac{1}{\rho!} \frac{d^{\rho}}{d\lambda^{\rho}} \left[\phi \left(\sum_{j=0}^{\infty} \lambda^j y_j \right) \right]_{\lambda=0} \quad (193)$$

Taking the derivative using chain rule we have:

$$= \frac{1}{\rho!} \frac{d^{\rho}}{d\lambda^{\rho}} \left[\phi \left(\sum_{j=0}^{\infty} \lambda^j y_j \right) \left(\sum_{j=0}^{\infty} \lambda^j D_t^{\sigma} y_j \right) \right]_{\lambda=0} \quad (194)$$

$$= \frac{1}{\rho!} \sum_{j=0}^{\rho} \binom{\rho}{j} j! y_j (\rho-j)! D_t^{\sigma} y_{\rho-j} \quad (195)$$

$$\frac{1}{\rho!} \sum_{j=0}^{\rho} \frac{\rho!}{j!(\rho-j)!} j! y_j (\rho-j)! D_t^{\sigma} y_{\rho-j} \quad (196)$$

therefore:

$$A_{\rho} = \frac{1}{\rho!} \sum_{j=0}^{\rho} y_j D_t^{\sigma} y_{\rho-j} \quad (197)$$

Thus

$$A_0 = y_0 D_t^{\sigma} y_0 \quad (198)$$

$$A_1 = y_1 D_t^{\sigma} y_0 + y_0 D_t^{\sigma} y_1 \quad (199)$$

$$A_2 = y_2 D_t^\sigma y_0 + y_1 D_t^\sigma y_1 + y_0 D_t^\sigma y_2 \quad (200)$$

$$A_3 = y_3 D_t^\sigma y_0 + y_2 D_t^\sigma y_1 + y_1 D_t^\sigma y_2 + y_0 D_t^\sigma y_3 \quad (201)$$

Using the recursive relation, we have:

$$y_0 = j^{\hat{\phi}}(1) \quad (202)$$

$$= \frac{1}{\Gamma(\hat{\phi})} \int_0^x (x-t)^{\hat{\phi}-1} dt \quad (203)$$

$$= \frac{1}{\Gamma(\hat{\phi})} \int_0^x \left(1 - \frac{t}{x}\right)^{\hat{\phi}-1} x^{\hat{\phi}-1} dt \quad (204)$$

Let $b = \frac{t}{x}$, $dt = xdb$ $t = bx$ when $t = 0$, $b = 0$ when $t = x$, $b = 1$, we have:

$$\frac{1}{\Gamma(\hat{\phi})} \int_0^1 (1-b)^{\hat{\phi}-1} x^{\hat{\phi}-1} x db \quad (205)$$

$$\frac{x^{\hat{\phi}}}{\Gamma(\hat{\phi})} \int_0^1 (1-b)^{\hat{\phi}-1} db \quad (206)$$

$$\frac{x^{\hat{\phi}}}{\Gamma(\hat{\phi})} \frac{(1-b)^{\hat{\phi}}}{\hat{\phi}} \Big|_0^1 \quad (207)$$

$$\frac{x^{\hat{\phi}}}{\Gamma(\hat{\phi})} \frac{(-1)}{\hat{\phi}} \quad (208)$$

$$\frac{-x^{\hat{\phi}}}{\Gamma(\hat{\phi}+1)} \quad (209)$$

Where $\hat{\phi}\Gamma(\hat{\phi}) = \Gamma(\hat{\phi}+1)$ and let $t = x$, we have:

$$\frac{-t^{\hat{\phi}}}{\Gamma(\hat{\phi}+1)} \quad (210)$$

So let $\frac{1}{\Gamma(\hat{\phi}+1)} = a_0$ therefore

$$y_0 = -a_0 t^{\hat{\phi}} \quad (211)$$

When $\rho = 0$:

$$y_1(t) = j^{\hat{\phi}}(A_0), \quad A_0 = y_0 D_t^{\bar{\sigma}} y_0 \quad (212)$$

therefore:

$$y_1(t) = j^{\hat{\phi}}[y_0 D_t^{\bar{\sigma}} y_0] \quad (213)$$

Using the identity $D_t^{\bar{\sigma}} k^{\bar{\sigma}} = \frac{\Gamma(\hat{\phi}+1)}{\Gamma(\bar{\sigma}-\hat{\phi}+1)} k^{\bar{\sigma}-\hat{\phi}}$

$$\Rightarrow D_t^{\bar{\sigma}} y_0 = -D_t^{\bar{\sigma}} a_0 t^{\hat{\phi}} = -a_0 \frac{\Gamma(\hat{\phi}+1)}{\Gamma(\bar{\sigma}-\hat{\phi}+1)} t^{(\bar{\sigma}-\hat{\phi})} \quad (214)$$

So therefore:

$$y_1(t) = j^{\hat{\phi}}(A_0) = j^{\hat{\phi}} \left[-y_0 a_0 \frac{\Gamma(\hat{\phi}+1)}{\Gamma(\bar{\sigma}-\hat{\phi}+1)} t^{(\bar{\sigma}-\hat{\phi})} \right] \quad (215)$$

$$\frac{1}{\Gamma(\hat{\phi})} \int_0^x (x-t)^{\hat{\phi}-1} \left(-(-a_0(t)^{\hat{\phi}}) \right) a_0 \frac{\Gamma(\hat{\phi}+1)}{\Gamma(\bar{\sigma}-\hat{\phi}+1)} t^{(\hat{\phi}-\bar{\sigma})} dt \quad (216)$$

$$\frac{1}{\Gamma(\hat{\phi})} \int_0^x (x-t)^{\hat{\phi}-1} a_0(t)^{\hat{\phi}} \frac{1}{\Gamma(\hat{\phi}+1)} \frac{\Gamma(\hat{\phi}+1)}{\Gamma(\bar{\sigma}-\hat{\phi}+1)} t^{(\hat{\phi}-\bar{\sigma})} dt \quad (217)$$

$$\frac{a_0}{\Gamma(\hat{\phi})\Gamma(\bar{\sigma}-\hat{\phi}+1)} \int_0^x (x-t)^{\hat{\phi}-1} t^{(2\hat{\phi}-\bar{\sigma})} dt \quad (218)$$

$$\frac{a_0}{\Gamma(\hat{\phi})\Gamma(\bar{\sigma}-\hat{\phi}+1)} \int_0^x \left(1-\frac{x}{t}\right)^{\hat{\phi}-1} x^{\hat{\phi}-1} t^{(2\hat{\phi}-\bar{\sigma})} dt \quad (219)$$

Let $b = \frac{t}{x}$, $dt = xdb$ $t = bx$ when $t=0$, $b=0$ when $t=x$, $b=1$, we have:

$$\frac{a_0}{\Gamma(\hat{\phi})\Gamma(\hat{\phi}-\bar{\sigma}+1)} \int_0^1 (1-b)^{\hat{\phi}-1} x^{2\hat{\phi}-\bar{\sigma}} x^{\hat{\phi}-1} b^{(2\hat{\phi}-\bar{\sigma})} dt \quad (220)$$

$$\frac{a_0}{\Gamma(\hat{\phi})\Gamma(\hat{\phi}-\bar{\sigma}+1)} \int_0^1 (1-b)^{\hat{\phi}-1} x^{3\hat{\phi}-\bar{\sigma}} b^{(2\hat{\phi}-\bar{\sigma})} db \quad (221)$$

$$\frac{a_0 x^{3\hat{\phi}-\bar{\sigma}}}{\Gamma(\hat{\phi})\Gamma(\hat{\phi}-\bar{\sigma}+1)} \int_0^1 (1-b)^{\hat{\phi}-1} b^{(2\hat{\phi}-\bar{\sigma})} db \quad (222)$$

$$\frac{a_0 x^{3\hat{\phi}-\bar{\sigma}}}{\Gamma(\hat{\phi})\Gamma(\hat{\phi}-\bar{\sigma}+1)} \frac{\Gamma(\hat{\phi})\Gamma(2\hat{\phi}-\bar{\sigma}+1)}{\Gamma(\hat{\phi}+2\hat{\phi}-\bar{\sigma}+1)} \quad (223)$$

$$\frac{a_0 x^{3\hat{\phi}-\bar{\sigma}}}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} \frac{\Gamma(2\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-\bar{\sigma}+1)} \quad (224)$$

Let $x=t$, we have :

$$\frac{a_0 t^{3\hat{\phi}-\bar{\sigma}}}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} \frac{\Gamma(2\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-\bar{\sigma}+1)} \quad (225)$$

So let $\frac{a_0 t^{3\hat{\phi}-\bar{\sigma}}}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} \frac{\Gamma(2\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-\bar{\sigma}+1)} = a_1$ we have:

$$y_1(t) = a_1 t^{3\hat{\phi}-\bar{\sigma}} \quad (226)$$

When $\rho = 1$:

$$y_2(t) = j^{\hat{\phi}} A_1, \quad A_1 = y_1 D_t^{\bar{\sigma}} y_0 + y_0 D_t^{\bar{\sigma}} y_1 \quad (227)$$

$$y_2(t) = j^{\hat{\phi}} [y_1 D_t^{\bar{\sigma}} y_0 + y_0 D_t^{\bar{\sigma}} y_1], \quad (228)$$

Similarly,

$$D_t^{\bar{\sigma}} y_0 = -D_t^{\bar{\sigma}} a_0 t^{\hat{\phi}} = -a_0 \frac{\Gamma(\hat{\phi}+1)}{\Gamma(\bar{\sigma}-\hat{\phi}+1)} \quad (229)$$

$$D_t^{\bar{\sigma}} y_1 = D_t^{\bar{\sigma}} a_1 t^{3\hat{\phi}-\bar{\sigma}} = a_1 \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} t^{3\hat{\phi}-2\bar{\sigma}} \quad (230)$$

$$\Rightarrow y_2(t) = j^{\hat{\phi}} \left[-a_1 t^{3\hat{\phi}-\bar{\sigma}} \frac{a_0 \Gamma(\hat{\phi}+1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} t^{\hat{\phi}-\bar{\sigma}} - a_0 t^{\hat{\phi}} \frac{a_1 \Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} t^{3\hat{\phi}-2\bar{\sigma}} \right] \quad (231)$$

$$\Rightarrow y_2(t) = \frac{1}{\Gamma(\hat{\phi})} \int_0^x (x-t)^{\hat{\phi}-1} \left[-a_1 t^{4\hat{\phi}-2\bar{\sigma}} \frac{a_0 \Gamma(\hat{\phi}+1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} - a_0 t^{4\hat{\phi}-2\bar{\sigma}} \frac{a_1 \Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} \right] dt \quad (232)$$

$$\Rightarrow y_2(t) = \frac{1}{\Gamma(\hat{\phi})} \int_0^x (x-t)^{\hat{\phi}-1} - a_1 a_0 t^{4\hat{\phi}-2\bar{\sigma}} \left[\frac{\Gamma(\hat{\phi}+1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} \right] dt \quad (233)$$

$$y_2(t) = \left[\frac{\Gamma(\hat{\phi}+1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} \right] \frac{-a_1 a_0}{\Gamma(\hat{\phi})} \int_0^x (x-t)^{\hat{\phi}-1} t^{4\hat{\phi}-2\bar{\sigma}} dt \quad (234)$$

Let $b = \frac{t}{x}$, $dt = xdb$ $t = bx$ when $t = 0$, $b = 0$ when $t = x$, $b = 1$, we have:

$$y_2(t) = \left[\frac{\Gamma(\hat{\phi}+1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} \right] \frac{-a_1 a_0}{\Gamma(\hat{\phi})} \int_0^1 \left(1 - \frac{t}{x}\right)^{\hat{\phi}-1} x^{\hat{\phi}-1} t^{4\hat{\phi}-2\bar{\sigma}} dt \quad (235)$$

$$y_2(t) = \left[\frac{\Gamma(\hat{\phi}+1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} \right] \frac{-a_1 a_0}{\Gamma(\hat{\phi})} \int_0^1 (1-b)^{\hat{\phi}-1} x^{\hat{\phi}-1} x^{4\hat{\phi}-2\bar{\sigma}} b^{4\hat{\phi}-2\bar{\sigma}} x db \quad (236)$$

$$y_2(t) = \left[\frac{\Gamma(\hat{\phi}+1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} \right] \frac{-a_1 a_0}{\Gamma(\hat{\phi})} \int_0^1 (1-b)^{\hat{\phi}-1} x^{5\hat{\phi}-2\bar{\sigma}} b^{4\hat{\phi}-2\bar{\sigma}} x db \quad (237)$$

$$y_2(t) = \left[\frac{\Gamma(\hat{\phi}+1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} \right] \frac{-a_1 a_0 x^{5\hat{\phi}-2\bar{\sigma}}}{\Gamma(\hat{\phi})} \int_0^1 (1-b)^{\hat{\phi}-1} b^{4\hat{\phi}-2\bar{\sigma}} x db \quad (238)$$

$$y_2(t) = \left[\frac{\Gamma(\hat{\phi}+1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} \right] \frac{-a_1 a_0 x^{5\hat{\phi}-2\bar{\sigma}}}{\Gamma(\hat{\phi})} \frac{\Gamma(\hat{\phi})\Gamma(4\hat{\phi}-2\bar{\sigma}+1)}{\Gamma(5\hat{\phi}-2\bar{\sigma}+1)} \quad (239)$$

$$y_2(t) = \left[\frac{\Gamma(\hat{\phi}+1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} \right] \frac{-a_1 a_0 x^{5\hat{\phi}-2\bar{\sigma}} \Gamma(4\hat{\phi}-2\bar{\sigma}+1)}{\Gamma(5\hat{\phi}-2\bar{\sigma}+1)} \quad (240)$$

Let $x=t$ we have:

$$y_2(t) = \left[\frac{\Gamma(\hat{\phi}+1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} \right] \frac{-a_1 a_0 t^{5\hat{\phi}-2\bar{\sigma}} \Gamma(4\hat{\phi}-2\bar{\sigma}+1)}{\Gamma(5\hat{\phi}-2\bar{\sigma}+1)} \quad (241)$$

Let

$$\left[\frac{\Gamma(\hat{\phi}+1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} \right] \frac{\Gamma(4\hat{\phi}-2\bar{\sigma}+1)}{\Gamma(5\hat{\phi}-2\bar{\sigma}+1)} = a_2 \quad (242)$$

Therefore:

$$y_2 = -a_2 t^{5\hat{\phi}-2\bar{\sigma}} \quad (243)$$

When $\rho = 2$ we have:

$$y_3(t) = j^{\hat{\phi}} A_2 = j^{\hat{\phi}} \left[y_2 D_t^{\bar{\sigma}} y_0 + y_1 D_t^{\bar{\sigma}} y_1 + y_0 D_t^{\bar{\sigma}} y_2 \right] \quad (244)$$

Where:

$$D_t^{\bar{\sigma}} y_0 = -D_t^{\bar{\sigma}} a_0 t^{\hat{\phi}} = \frac{-a_0 \Gamma(\hat{\phi}+1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} t^{\hat{\phi}-\bar{\sigma}} \quad (245)$$

$$D_t^{\bar{\sigma}} y_1 = D_t^{\bar{\sigma}} a_1 t^{3\hat{\phi}-\bar{\sigma}} = \frac{a_1 \Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-\bar{\sigma}+1)} t^{3\hat{\phi}-2\bar{\sigma}} \quad (246)$$

$$D_t^{\bar{\sigma}} y_2 = -D_t^{\bar{\sigma}} a_1 t^{3\hat{\phi}-\bar{\sigma}} = \frac{-a_2 \Gamma(5\hat{\phi}-2\bar{\sigma}+1)}{\Gamma(5\hat{\phi}-3\bar{\sigma}+1)} t^{5\hat{\phi}-2\bar{\sigma}} \quad (247)$$

$$y_3(t) = j^{\hat{\phi}} \left[\begin{aligned} & a_2 t^{5\hat{\phi}-2\bar{\sigma}} \frac{a_0 \Gamma(\hat{\phi}-1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} t^{\hat{\phi}-\bar{\sigma}} + a_1 t^{3\hat{\phi}-\bar{\sigma}} \frac{a_1 \Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} t^{3\hat{\phi}-2\bar{\sigma}} \\ & + a_0 t^{\hat{\phi}} \frac{a_2 \Gamma(5\hat{\phi}-2\bar{\sigma}+1)}{\Gamma(5\hat{\phi}-3\bar{\sigma}+1)} t^{5\hat{\phi}-2\bar{\sigma}} \end{aligned} \right] \quad (248)$$

$$y_3(t) = j^{\hat{\phi}} \left[\begin{aligned} & a_2 t^{6\hat{\phi}-3\bar{\sigma}} \frac{a_0 \Gamma(\hat{\phi}-1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + a_1^2 t^{6\hat{\phi}-3\bar{\sigma}} \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} t^{6\hat{\phi}-3\bar{\sigma}} \\ & + a_0 \frac{a_2 \Gamma(5\hat{\phi}-2\bar{\sigma}+1)}{\Gamma(5\hat{\phi}-3\bar{\sigma}+1)} t^{6\hat{\phi}-2\bar{\sigma}} \end{aligned} \right] \quad (249)$$

$$y_3(t) = \frac{1}{\Gamma(\hat{\phi})} \int_0^x (x-t)^{\hat{\phi}-1} t^{6\hat{\phi}-3\bar{\sigma}} \times \left[a_2 \frac{a_0 \Gamma(\hat{\phi}-1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + a_1^2 \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} + a_0 \frac{a_2 \Gamma(5\hat{\phi}-2\bar{\sigma}+1)}{\Gamma(5\hat{\phi}-3\bar{\sigma}+1)} \right] dt \quad (250)$$

$$y_3(t) = \left[a_2 \frac{a_0 \Gamma(\hat{\phi}-1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + a_1^2 \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} + a_0 \frac{a_2 \Gamma(5\hat{\phi}-2\bar{\sigma}+1)}{\Gamma(5\hat{\phi}-3\bar{\sigma}+1)} \right] \times \frac{1}{\Gamma(\hat{\phi})} \int_0^x (x-t)^{\hat{\phi}-1} t^{6\hat{\phi}-3\bar{\sigma}} dt \quad (251)$$

$$y_3(t) = \left[a_2 \frac{a_0 \Gamma(\hat{\phi}-1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + a_1^2 \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} + a_0 \frac{a_2 \Gamma(5\hat{\phi}-2\bar{\sigma}+1)}{\Gamma(5\hat{\phi}-3\bar{\sigma}+1)} \right] \times \frac{1}{\Gamma(\hat{\phi})} \int_0^x \left(1 - \frac{t}{x}\right)^{\hat{\phi}-1} x^{\hat{\phi}-1} t^{6\hat{\phi}-3\bar{\sigma}} dt \quad (252)$$

Let $b = \frac{t}{x}$, $dt = xdb$ $t = bx$ when $t = 0$, $b = 0$ when $t = x$, $b = 1$, we have:

$$y_3(t) = \left[a_2 \frac{a_0 \Gamma(\hat{\phi}-1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + a_1^2 \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} + a_0 \frac{a_2 \Gamma(5\hat{\phi}-2\bar{\sigma}+1)}{\Gamma(5\hat{\phi}-3\bar{\sigma}+1)} \right] \times \frac{1}{\Gamma(\hat{\phi})} \int_0^1 (1-b)^{\hat{\phi}-1} x^{7\hat{\phi}-3\bar{\sigma}} b^{6\hat{\phi}-3\bar{\sigma}} db \quad (253)$$

$$y_3(t) = \left[a_2 \frac{a_0 \Gamma(\hat{\phi}-1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + a_1^2 \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} + a_0 \frac{a_2 \Gamma(5\hat{\phi}-2\bar{\sigma}+1)}{\Gamma(5\hat{\phi}-3\bar{\sigma}+1)} \right] \times \frac{x^{7\hat{\phi}-3\bar{\sigma}}}{\Gamma(\hat{\phi})} \int_0^1 (1-b)^{\hat{\phi}-1} b^{6\hat{\phi}-3\bar{\sigma}} db \quad (254)$$

$$y_3(t) = \left[a_2 \frac{a_0 \Gamma(\hat{\phi}-1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + a_1^2 \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} + a_0 \frac{a_2 \Gamma(5\hat{\phi}-2\bar{\sigma}+1)}{\Gamma(5\hat{\phi}-3\bar{\sigma}+1)} \right] \times \frac{x^{7\hat{\phi}-3\bar{\sigma}} \Gamma(\hat{\phi}) \Gamma(6\hat{\phi}-3\bar{\sigma}+1)}{\Gamma(\hat{\phi}) \Gamma(7\hat{\phi}-3\bar{\sigma}+1)} \quad (255)$$

$$y_3(t) = \left[a_2 \frac{a_0 \Gamma(\hat{\phi}-1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + a_1^2 \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} + a_0 \frac{a_2 \Gamma(5\hat{\phi}-2\bar{\sigma}+1)}{\Gamma(5\hat{\phi}-3\bar{\sigma}+1)} \right] \times \frac{x^{7\hat{\phi}-3\bar{\sigma}} \Gamma(6\hat{\phi}-3\bar{\sigma}+1)}{\Gamma(7\hat{\phi}-3\bar{\sigma}+1)} \quad (256)$$

Let $x=t$ we have:

$$y_3(t) = \left[a_2 \frac{a_0 \Gamma(\hat{\phi}-1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + a_1^2 \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} + a_0 \frac{a_2 \Gamma(5\hat{\phi}-2\bar{\sigma}+1)}{\Gamma(5\hat{\phi}-3\bar{\sigma}+1)} \right] \frac{t^{7\hat{\phi}-3\bar{\sigma}} \Gamma(6\hat{\phi}-3\bar{\sigma}+1)}{\Gamma(7\hat{\phi}-3\bar{\sigma}+1)} \quad (257)$$

Let:

$$\left[a_2 \frac{a_0 \Gamma(\hat{\phi}-1)}{\Gamma(\hat{\phi}-\bar{\sigma}+1)} + a_1^2 \frac{\Gamma(3\hat{\phi}-\bar{\sigma}+1)}{\Gamma(3\hat{\phi}-2\bar{\sigma}+1)} + a_0 \frac{a_2 \Gamma(5\hat{\phi}-2\bar{\sigma}+1)}{\Gamma(5\hat{\phi}-3\bar{\sigma}+1)} \right] = a_3 \quad (258)$$

Therefore

$$y_3 = a_3 t^{7\hat{\phi}-3\bar{\sigma}} \quad (259)$$

The solution is in series form express below as:

$$y(t) = -a_0 t^{\hat{\phi}} + a_1 t^{3\hat{\phi}-\bar{\sigma}} - a_1 t^{5\hat{\phi}-2\bar{\sigma}} + a_1 t^{7\hat{\phi}-3\bar{\sigma}} - \dots \quad (260)$$

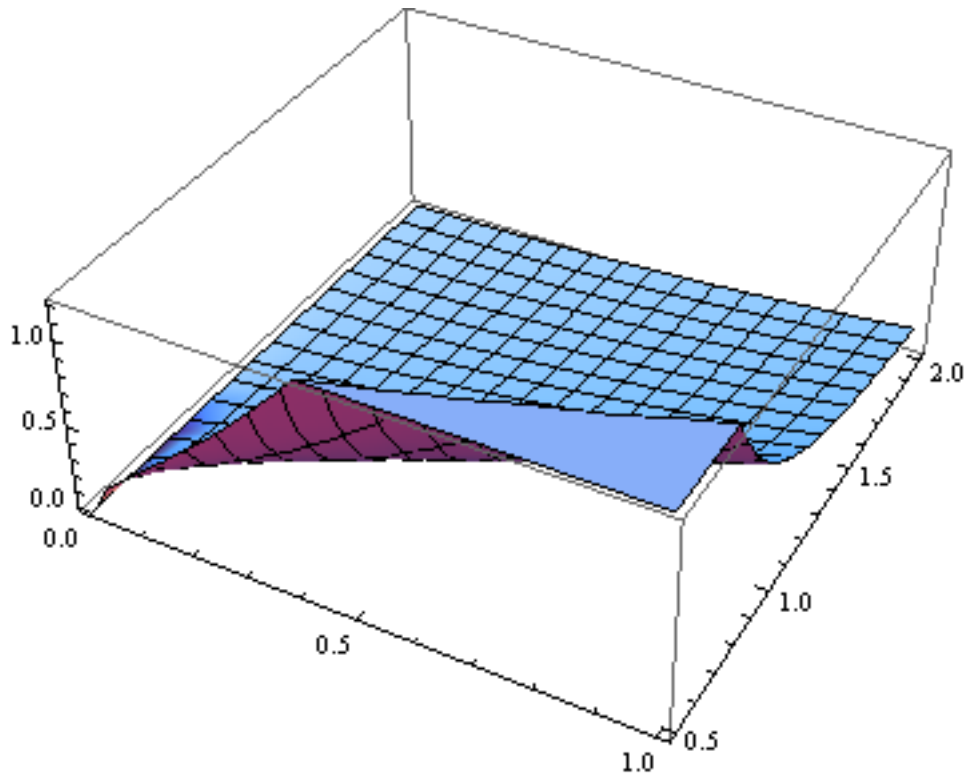


Figure 4. Solution of Example 4

The solution obtained is in conformity with the solution obtained by Shawagfeh [16] when $\bar{\sigma} = 0$, but the solution above is obtained by varying the value of $\hat{\phi}$ within the interval $0.5 \leq \hat{\phi} \leq 2$ and $\bar{\sigma} = 0$. This solution is only considered for four terms, more terms can be consider to improve the solution.

Chapter 4

DISCUSSION OF RESULTS

4.1 Conclusion

The effectiveness of ADM technique on multi-order fractional differential equations of both linear and non linear type was explored. Four different examples were considered, the results obtained were compared to those existing in literature for evaluation purpose.

Several of researchers have applied ADM technique to solve several problems existing in real life situation as written in Chapter 1, which contains the preamble. Since the introduction of the technique about three decade ago, sources confirm the effectiveness, efficient and the accuracy of ADM technique.

However, this thesis work only highlighted it advantages without comparing it pros and cons.

In the second Chapter, rudimentary analysis of ADM technique with the consideration of a very important special function known as the gamma function was reviewed. In Chapter 3 we considered four examples and the estimation of these examples were easily carried out and computed without the aid of computer. The solution obtained in the study is in the form of convergence series which exhibit some recursive relationship.

It is evidently clear that there exist a relationship of some sorts between the simple harmonic motion and the sine wave as shown in this thesis work, therefore this study is applicable in the music industries for fine tuning and production of various musical instruments such as microphones, loudspeaker, acoustic instruments like guitars, pianos, violins e.t.c. Also in the auto-mobile industries, the technology behind the shock absorbers of our vehicles depends greatly on this study or similar studies.

Electrical power generation is also an area of application due to electromagnetic wave. The operation of gravimeters for the detection of differences in the value of gravity at that location, known as gravity surveys is extensively useful in the oil, gas and mining industry to locate crude oil and precious metal deposit. The fourth examined equation displays an important advantage of ADM technique, inspite of the easy computation there is no need for linearization or assumption of any sort

In general, the Adomian's Decomposition Method (ADM) is a convenient tool, it can be applied directly to problems. It also demonstrates computational ease which can be computed manually.

REFERNCES

- [1] Achar, B. N., Hanneken, J. W., Enck, T., & Clarke, T. (2001). Dynamics of the fractional oscillator. *Physica A: Statistical Mechanics and its Applications*, 297(3), 361-367.

- [2] Abdullah S. & Prabhat k. (2015). One solution of Multi- term fractional differential equation by Adomian's Decomposition Method. *Int. J of Science and Innovative Mathematical Research (IJSIMR)* Vol. 3, pp. (14-21).

- [3] Adomian, G. (1988). A review of the decomposition method in applied mathematics. *Journal of mathematical analysis and applications*, 135(2), 501-544.

- [4] Adomian, G. (1994). *Solving Frontier Problems of Physics: The Decomposition Method*, Kluwer Academic Publishers, Boston, MA.

- [5] Babolian, E., & Bizar, J. (2002). On the order of convergence of Adomian's method. *Applied Mathematics and Computational*, 130(2), 383-387.

- [6] Cherruault, Y., Adomian, G., Abbaoui, K., & Rach, R. (1995). Further remarks on convergence of decomposition method. *International journal of bio-medical computing*, 38(1), 89-93.

- [7] Hashim, I. & Wang, L. (2006). Comments on “a new algorithm for solving Classical Blassus equation” by L. Wang. *Applied Mathematics and Computer*, 176(2): 700-703.
- [8] Kemple, S., & Beyer, H. (1997). Global and causal solutions of fractional differential equations in: *Transform Method and Special Functions*. In Varna 96, Proceeding of the 2nd International Workshop (SCTP), Singapore.
- [9] Lesnic, D. (2002). Convergence of Adomian’s decomposition method: periodic temperatures. *Computers & Mathematics with Applications*, 44(1), 13-24.
- [10] Miller, K. S., & Ross, B. (2005). *An Introduction to Fractional Differential Equations by the Decomposition Method*. *Appl. Math. Comput.*, 163(3), 1351-1365.
- [11] Momani, S. (2006). A Numerical Scheme for the Solution of multi-order fractional differential equations. *Appl. Maths and Comp.*, 183(2), 761-770.
- [12] Momani, S., & Odibat, Z. (2008). Numerical solutions of the space-time fractional advection-dispersion equation. *Numerical Methods for Partial Differential Equations*, 24(6), 1416-1429.

[13] Navaed I., Syed T. (2013). Decomposition Method for fractional differential equations (PDEs) using Laplace transformation. *International Journal of Physical Sciences*, 8(16), 684-688.

[14] Shawagfeh N.T. (2002). Analytical approximate Solution for non-linear fractional differential equations. *Appl. Math. Comput.*, 131(2), 517-529.